

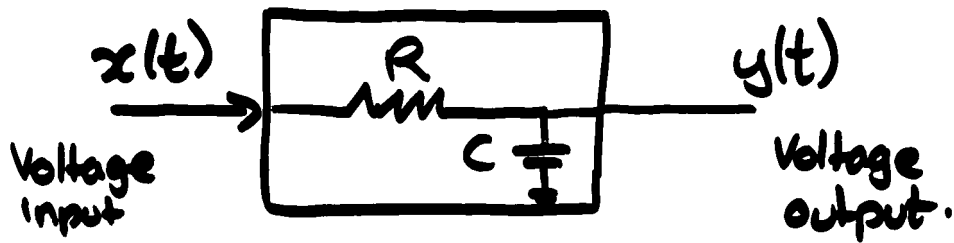
CONVOLUTION INTEGRAL

A RECIPE -

$$y(t) = \int x(\tau) h(t-\tau) d\tau$$

- ① Plot $x(\tau)$, $h(\tau)$ and $\tilde{u}(\tau) = h(-\tau)$
- ② Start with t large and negative
- ③ Plot $\tilde{u}(\tau-t) = h(t-\tau)$ and use your graph to help you find a functional form for $w_t(\tau) = x(\tau) h(t-\tau)$
- ④ Increase t until your formula is no longer valid. Record this value as one of the t_j 's in the previous formula for $y(t)$.
- ⑤ Repeat ③ and ④ until all functional forms of $w_t(\tau)$ have been identified and all t_j 's identified. Usually this requires t to be large and positive.
- ⑥ On each interval find $f_j(t) = \int w_t(\tau) d\tau$
- ⑦ Sanity check. If $x(t)$ and $h(t)$ have no "infinite" discontinuities then

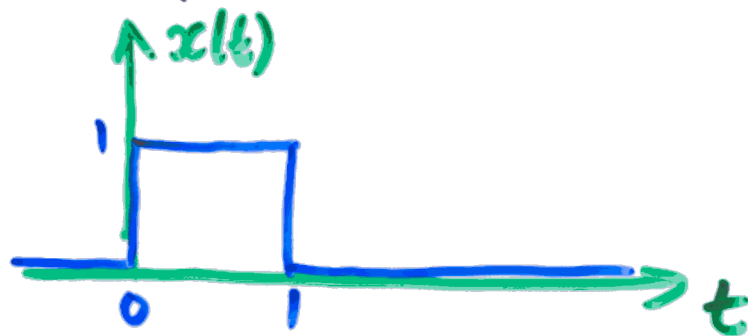
REALISTIC EXAMPLE (Similar to Ex 2.7)



The impulse response of this circuit is

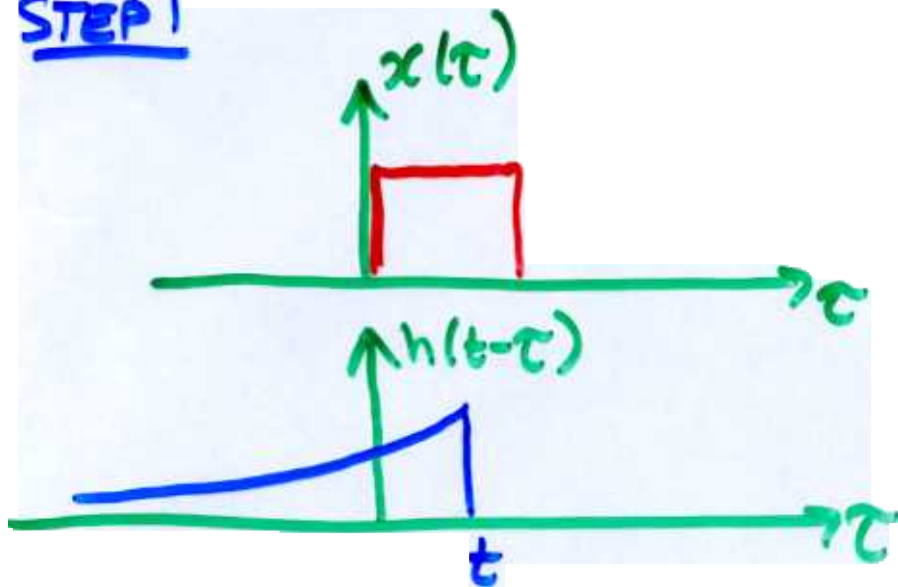


What is the output $y(t)$, when the input is a square pulse



The answer to questions such as this is fundamental to the determination of how fast chips can run + how fast we can communicate

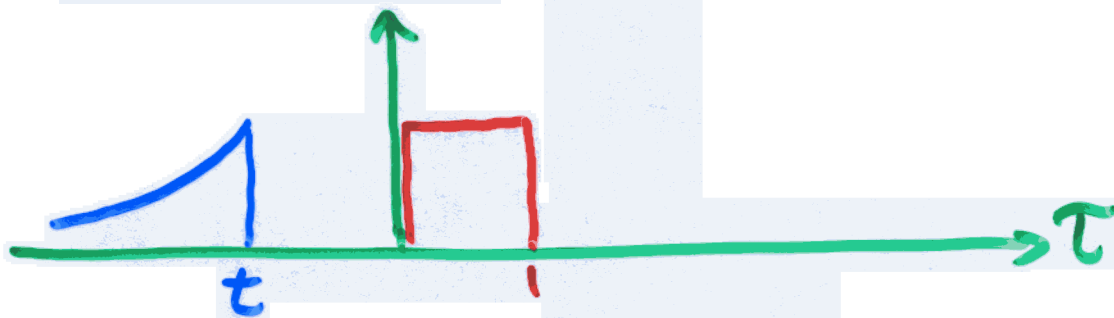
STEP 1



$$h(t) = e^{-at} u(t)$$

note $h(t-\tau) = e^{-a(t-\tau)} u(t-\tau)$

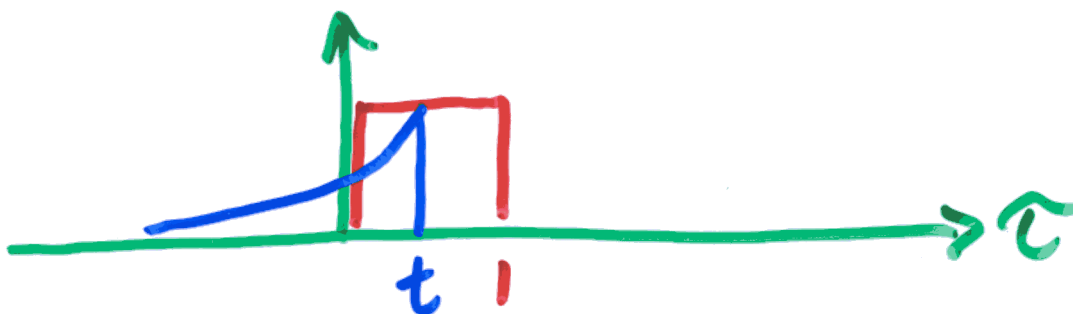
STEP 3, for t large and negative

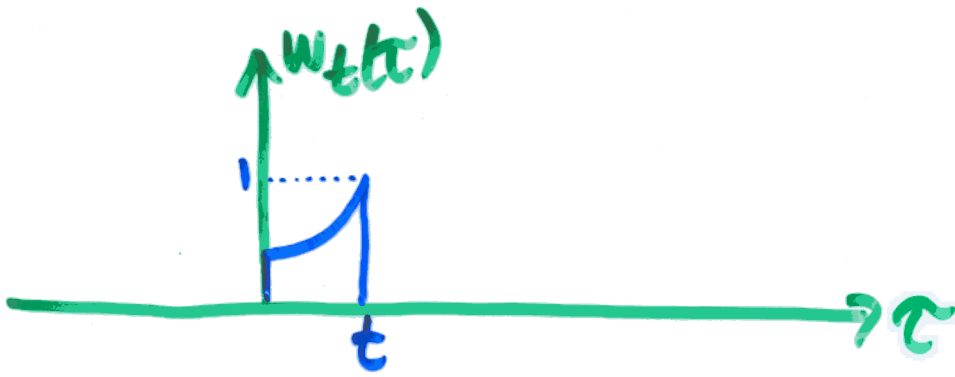


Hence $w_t(\tau) = 0$

STEP 4 This formula is valid until $t = 0$

STEP 3, for $t \geq 0$

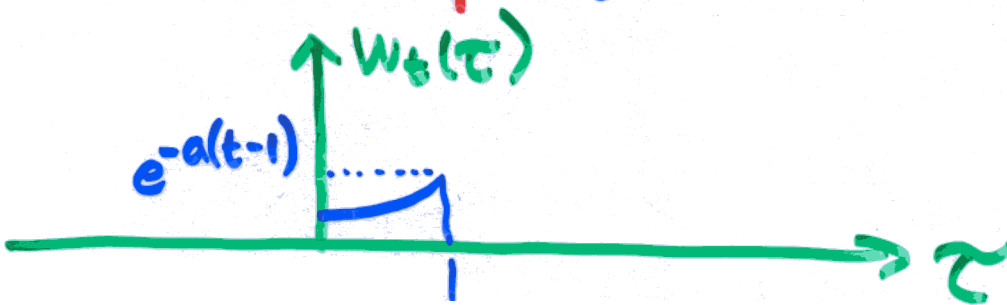
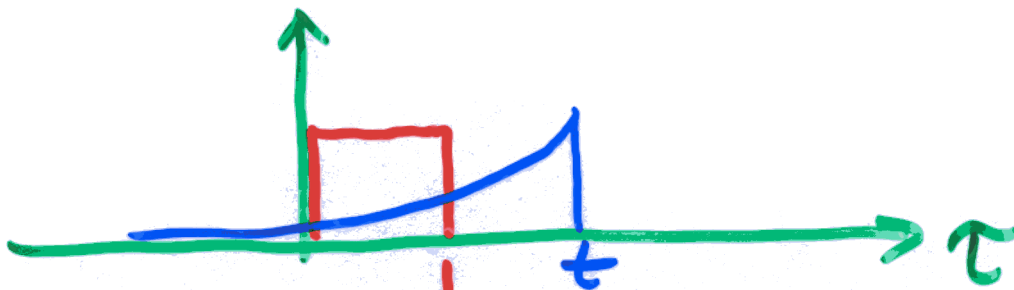




Hence $w_t(\tau) = \begin{cases} 0 & \tau < 0 \\ e^{-a(t-\tau)} & 0 \leq \tau < t \\ 0 & \tau \geq t \end{cases}$

Formula is valid until t

Step 3, for $t \geq 1$



$\Rightarrow w_t(\tau) = \begin{cases} 0 & \tau < 0 \\ e^{-a(t-\tau)} & 0 \leq \tau < 1 \\ 0 & \tau \geq 1 \end{cases}$

This formula is valid for $t \geq 0$

Hence

$$w_t(\tau) = \begin{cases} 0 & \text{for } \tau < 0 & \text{when } t < 0 \\ \begin{cases} e^{-a(t-\tau)} & 0 \leq \tau < t \\ 0 & \text{otherwise} \end{cases} & & \text{when } 0 \leq t < \infty \\ \begin{cases} e^{-a(t-\tau)} & 0 \leq \tau < \infty \\ 0 & \text{otherwise} \end{cases} & & \text{when } t \geq \infty \end{cases}$$

Step 5 $y(t) = \int_{-\infty}^{\infty} w_t(\tau) d\tau$

~~Result~~

when $t < 0$ $w_t(\tau) = 0 \Rightarrow y(t) = 0$

when $0 \leq t < \infty$

$$\begin{aligned} y(t) &= \int_0^t e^{-a(t-\tau)} d\tau \\ &= e^{-at} \int_0^t e^{a\tau} d\tau \\ &= e^{-at} \left[\frac{e^{a\tau}}{a} \right]_0^t \\ &= \frac{-e^{-at}}{a} \end{aligned}$$

when $t \geq 1$

$$y(t) = \int_0^1 -a(t-\tau) d\tau$$
$$= \frac{(e^a - 1)}{a} e^{-at}$$

Summarise

$$y(t) = \begin{cases} 0 & t < 0 \\ \frac{1-e^{-at}}{a} & 0 \leq t \leq 1 \\ \left(\frac{e^a-1}{a}\right)e^{-at} & t \geq 1 \end{cases}$$

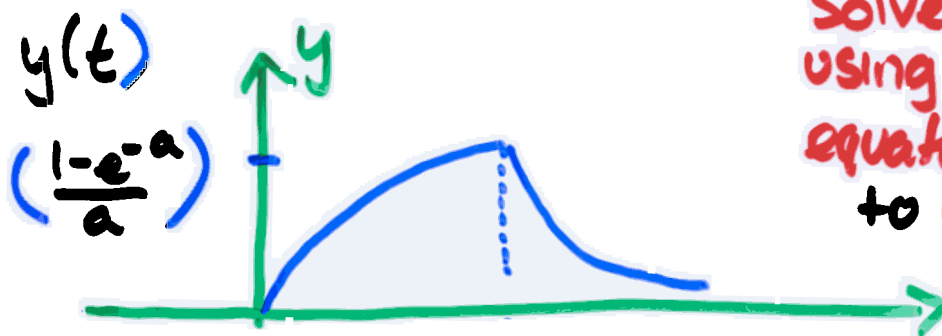
ty checks

$$y(0^-) = 0 ; y(0^+) = \frac{1}{a}$$

$$y(1^-) = \frac{1-e^{-a}}{a} ; y(1^+) = \frac{e^a-1}{a} e^{-a}$$
$$= \frac{1-e^{-a}}{a}$$

Passed!

PI



Solve using differential equations (2CI4) to confirm result

SUGGESTED HOMEWORK

DRILL PROBLEMS

2.2, 2.3

2.4 2.5

These problems have answers in the book