COMP ENG 4TL4: Digital Signal Processing

Notes for Lecture #23 Friday, October 31, 2003 <u>Modern window types</u> (have been derived based on optimality criteria):

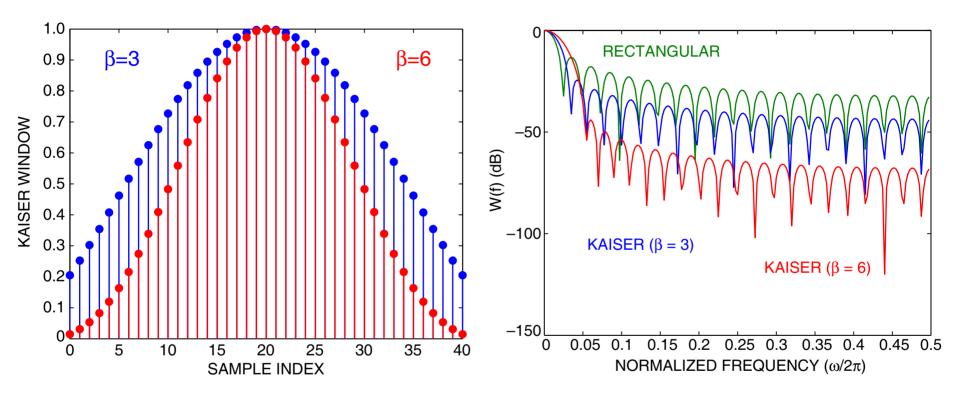
Kaiser window and Dolph-Chebyshev window:

minimize the width of the mainlobe under the constraints that:

- 1. the *window length be fixed* and
- 2. the sidelobe levels not exceed a given value.

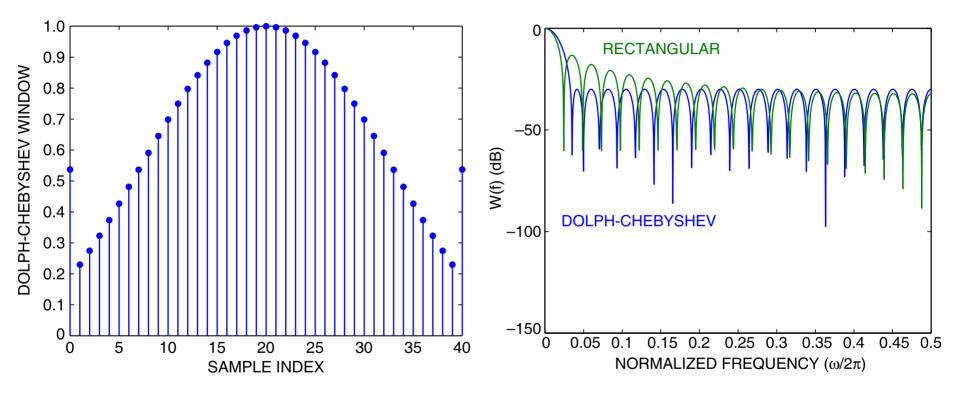
These windows provide more flexibility than the classical windows because a desired tradeoff between mainlobe width and sidelobe levels can be achieved!

Kaiser window compared to the rectangular window in the frequency domain: (M = 40)



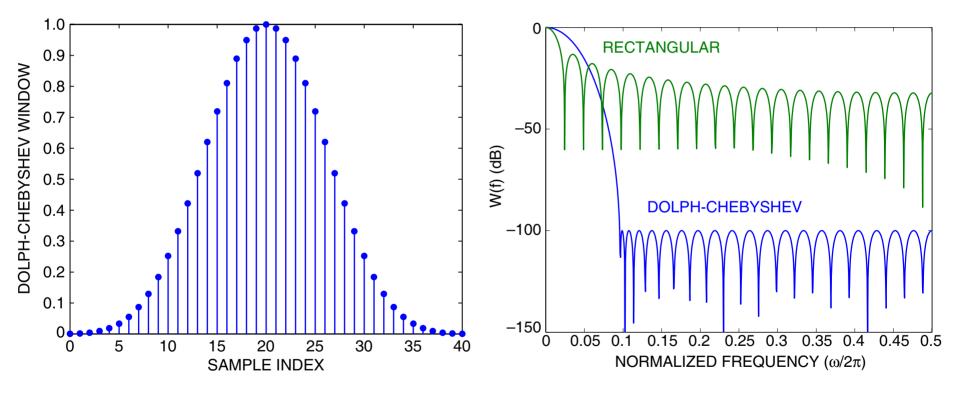
The <u>Kaiser window</u> has two parameters: the length M+1 and a shape parameter β . The value of β required to achieve a particular maximal sidelobe level can be obtained from an empirically-derived formula—see *Oppenheim and Schafer* pp. 474–485 for more details.

<u>Dolph-Chebyshev window with -30 dB of ripple compared to the rectangular window in the frequency domain:</u> (M = 40)



The <u>Dolph-Chebyshev window</u> has two parameters: the length M+1 and the desired sidelobe level. Note the equal levels of the sidelobes.

Dolph-Chebyshev window with -100 dB of ripple compared to the rectangular window in the frequency domain: (M = 40)



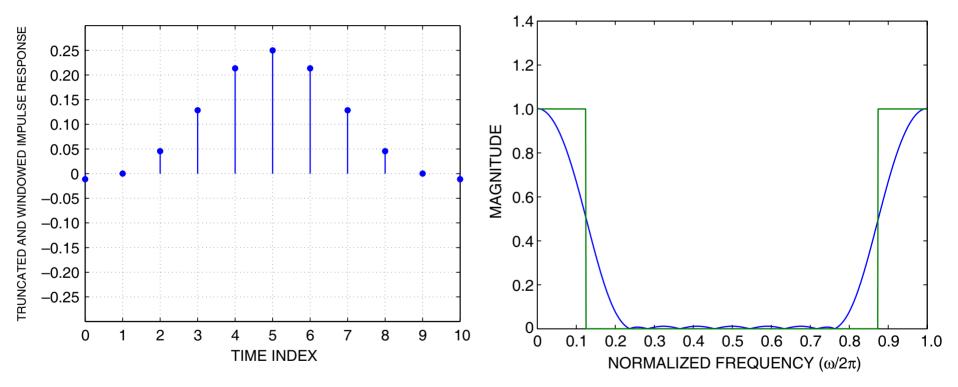
Now, let us take the <u>Dolph-Chebyshev window</u> and design our example lowpass filter using the window method with M = 10, M = 40, and M = 160.

Remember that:

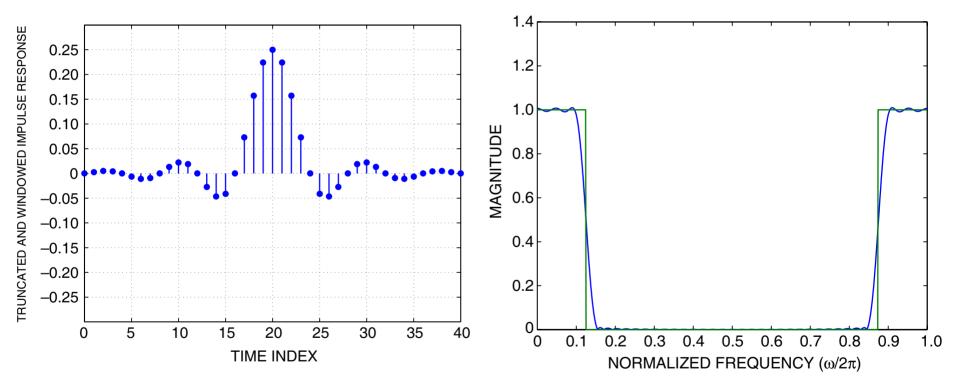
$$h_{\text{id}}[n] = \frac{\sin(\pi (n - M/2)/4)}{\pi (n - M/2)}.$$

We apply a Dolph-Chebyshev window of length M+1.

<u>Truncated and windowed impulse response and</u> <u>corresponding approximation of lowpass frequency response:</u> (window ripple -30 dB; M = 10)

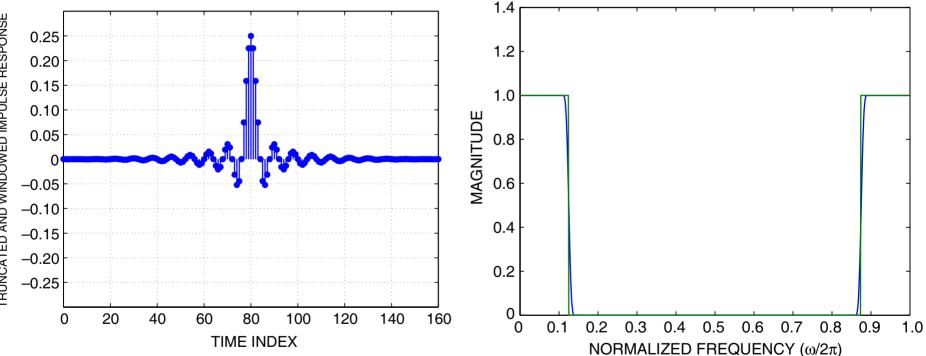


<u>Truncated and windowed impulse response and</u> <u>corresponding approximation of lowpass frequency response:</u> (window ripple -30 dB; M = 40)



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Truncated and windowed impulse response and corresponding approximation of lowpass frequency response: (window ripple –60 dB; M = 160)



There is no Gibbs phenomenon with the Dolph-Chebyshev window!

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<u>Optimization-based methods:</u> the idea is to find the best approximation to the ideal frequency response for a given fixed M.

<u>Question:</u> What should be our criterion for the "best" approximation?

<u>Answer #1:</u> How about minimizing the mean-square error?

$$\epsilon^{2} = \frac{1}{2\pi} \int_{-\pi}^{\pi} \left| H_{\mathsf{id}} \left(e^{j\omega} \right) - H \left(e^{j\omega} \right) \right|^{2} \, d\omega.$$

Unfortunately, the solution to this minimization problem is:

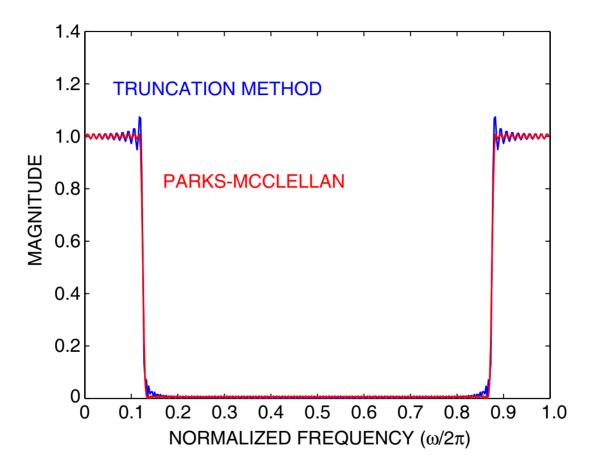
$$h[n] = \begin{cases} h_{\mathsf{id}}[n], & 0 \le n \le M, \\ 0, & n > M, \end{cases}$$

the truncation method, which we know suffers from the Gibbs phenomenon!

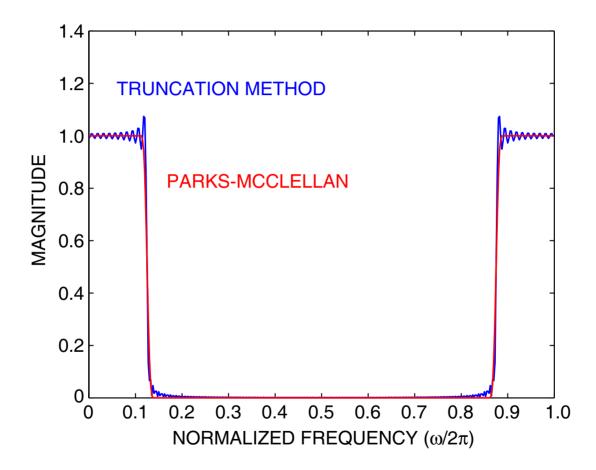
<u>Answer #2:</u> How about minimizing the maximum error?

This is referred to as the $\min \max$ strategy, and several algorithms have been developed to solve this problem.

The most widely used of these is the <u>Parks-McClellan</u> algorithm, often referred to (mistakenly) as the remez algorithm, which determines the optimal (in the minimax sense) equiripple FIR filter for a given desired frequency response. Parks-McClellan optimal (minimax) equiripple FIR filter lowpass frequency response: (M = 160)



If some nonzero passband ripple and stopband attenuation is permissible, then a very sharp transition region matching that of the truncation method can be obtained. Parks-McClellan optimal (minimax) equiripple FIR filter lowpass frequency response: (M = 160)



With just a slight relaxation of the slope of the transition region, the passband ripple and stopband attenuation can be dramatically reduced.