

# IMAGE-GUIDED SURGERY (IGS)



CongCong Yu

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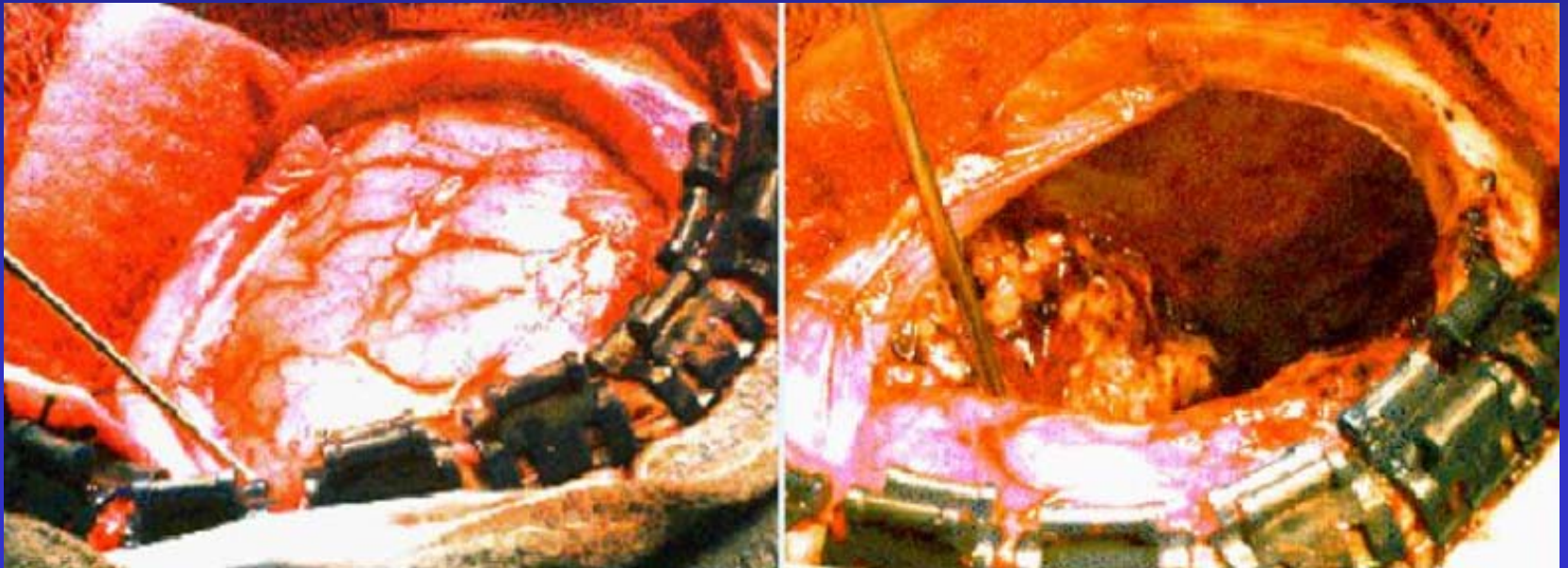
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# What is Image-Guided Surgery

- Surgical procedures that combine imaging instruments in real time such as computed tomography (CT scans), magnetic resonance imaging (MRIs) and light emitting diode cameras (LEDs)
- Allow surgeons to navigate their way through body with the help of three-dimensional images.

# Conventional Surgery

See the surface

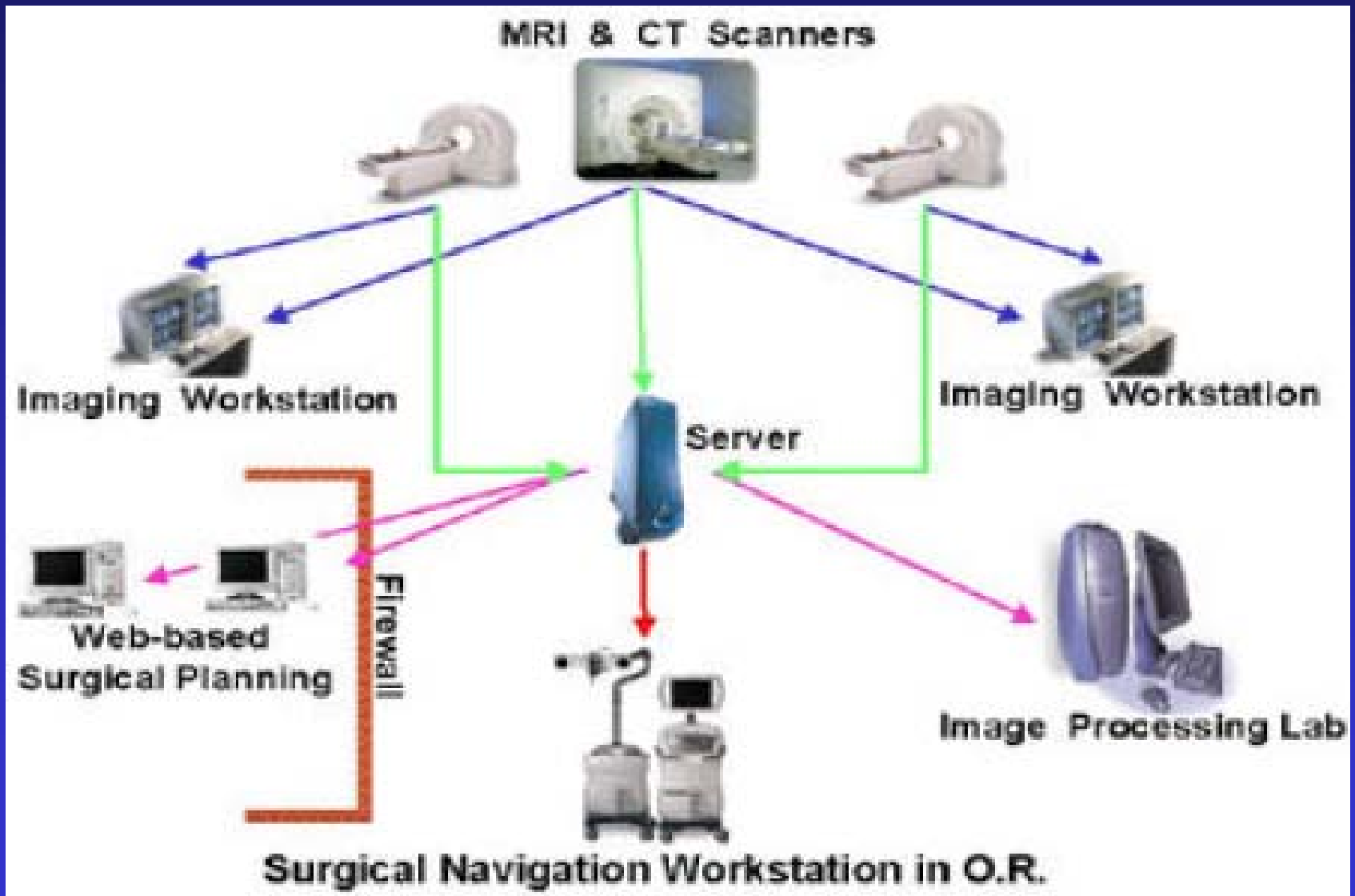


# IMAGE-GUIDED SURGERY

See under the surface



# IGS NETWORK

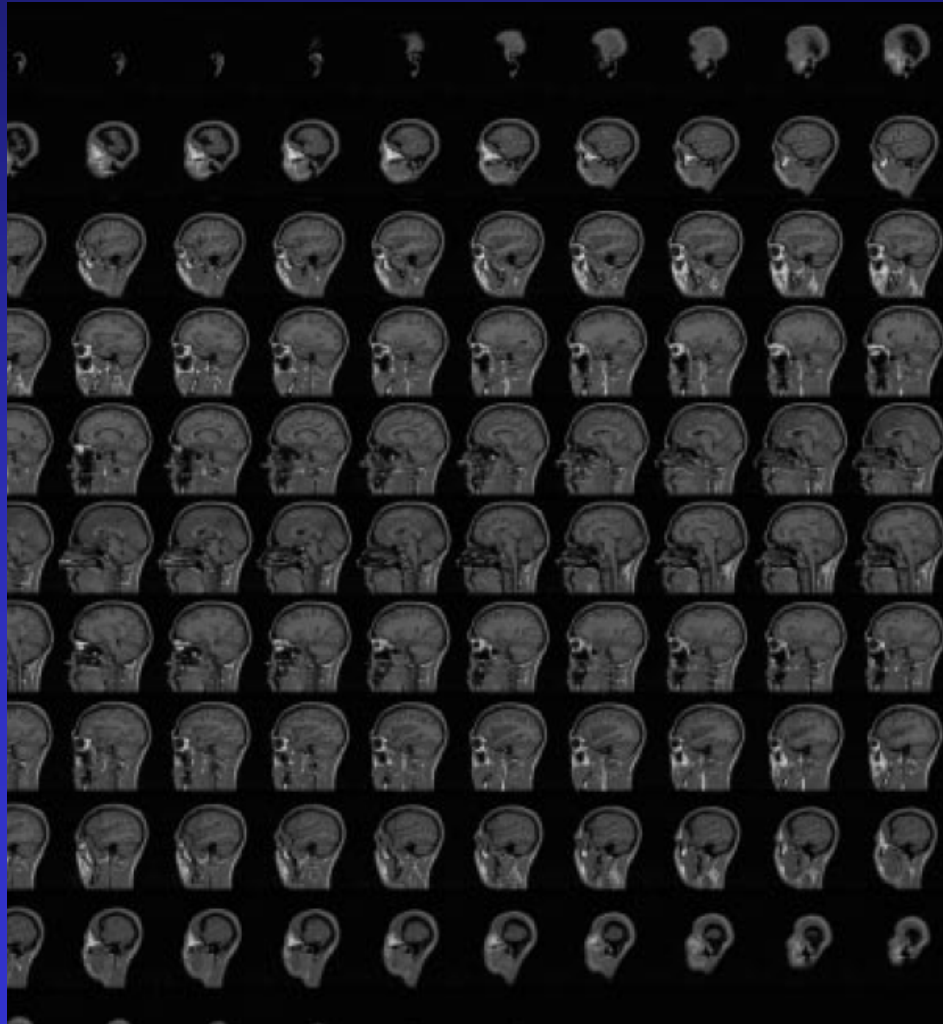


# Flowchart for IGS



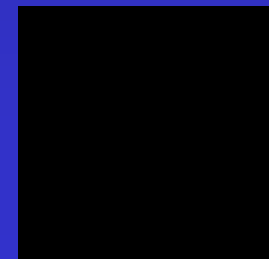


# Pre-operative image construction



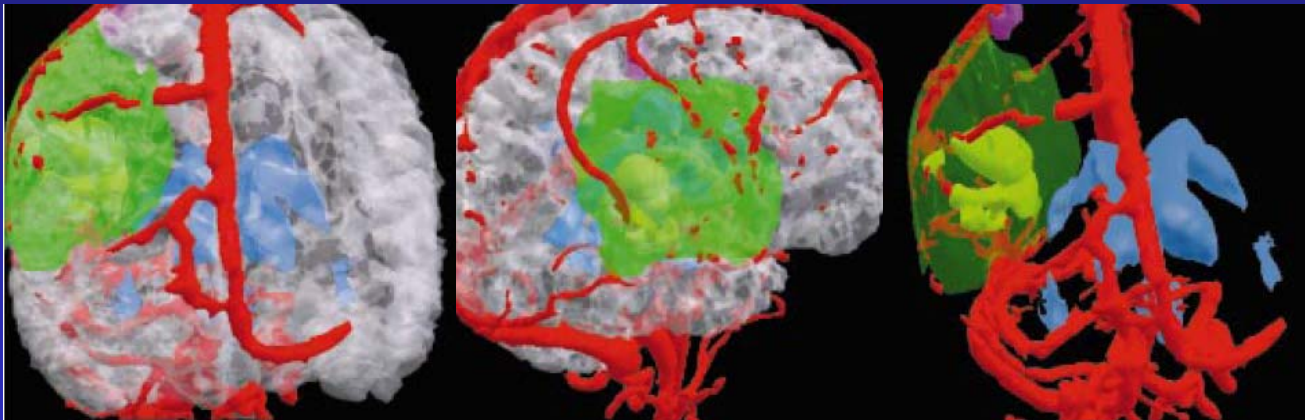
1. Internal scan from MRI and CT to obtain anatomical structure

Combine serial MRI scans to create the 3 dimensional volume



# Pre-operative image construction

2. Perform segmentation (label individual voxels in the volumetric scan by tissue type)

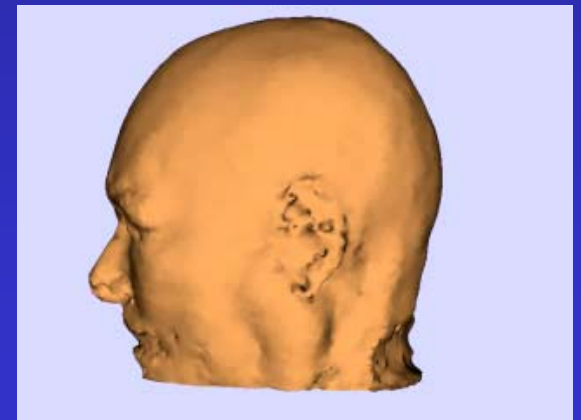
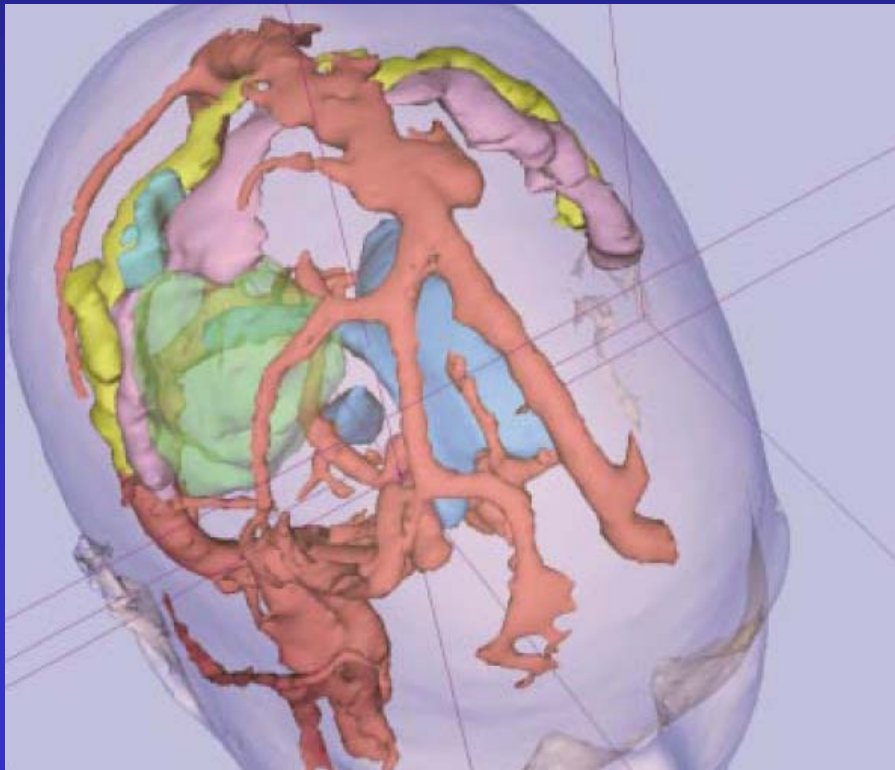


Different tissues emit different amounts of energy in response to MIR pulse and recorded as different brightness in MRI scan



# Pre-operative image construction

3. Construct 3D surface from the segmented MRI structures using surface rendering techniques



# Setup in operating room

Articulated Arm

Laser-Calibrated  
Video Camera

Sun UltraSPARC  
Workstation

Flashpoint  
Controller

Laser Scanner  
Hardware



Laser on a  
Stepper Motor

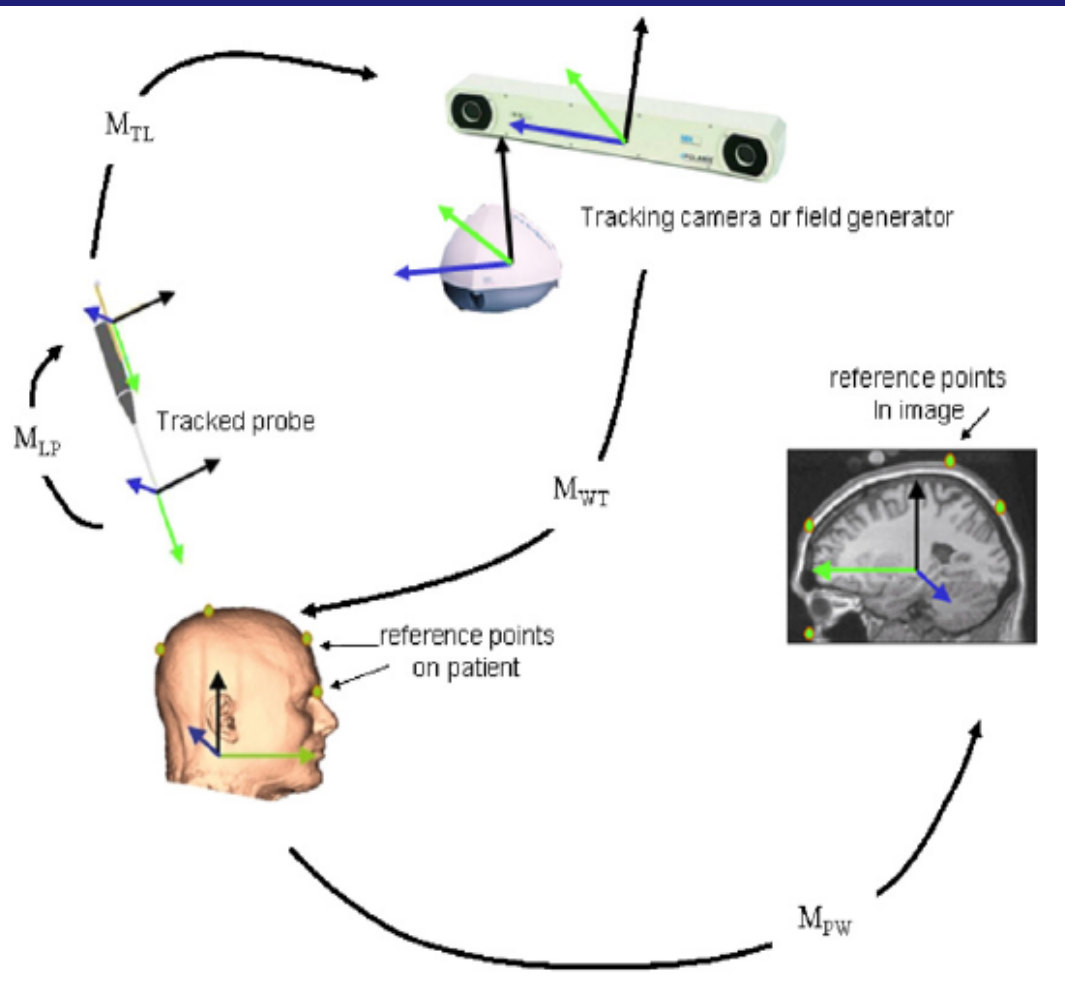
Flashpoint Bar

Author

# What is image registration

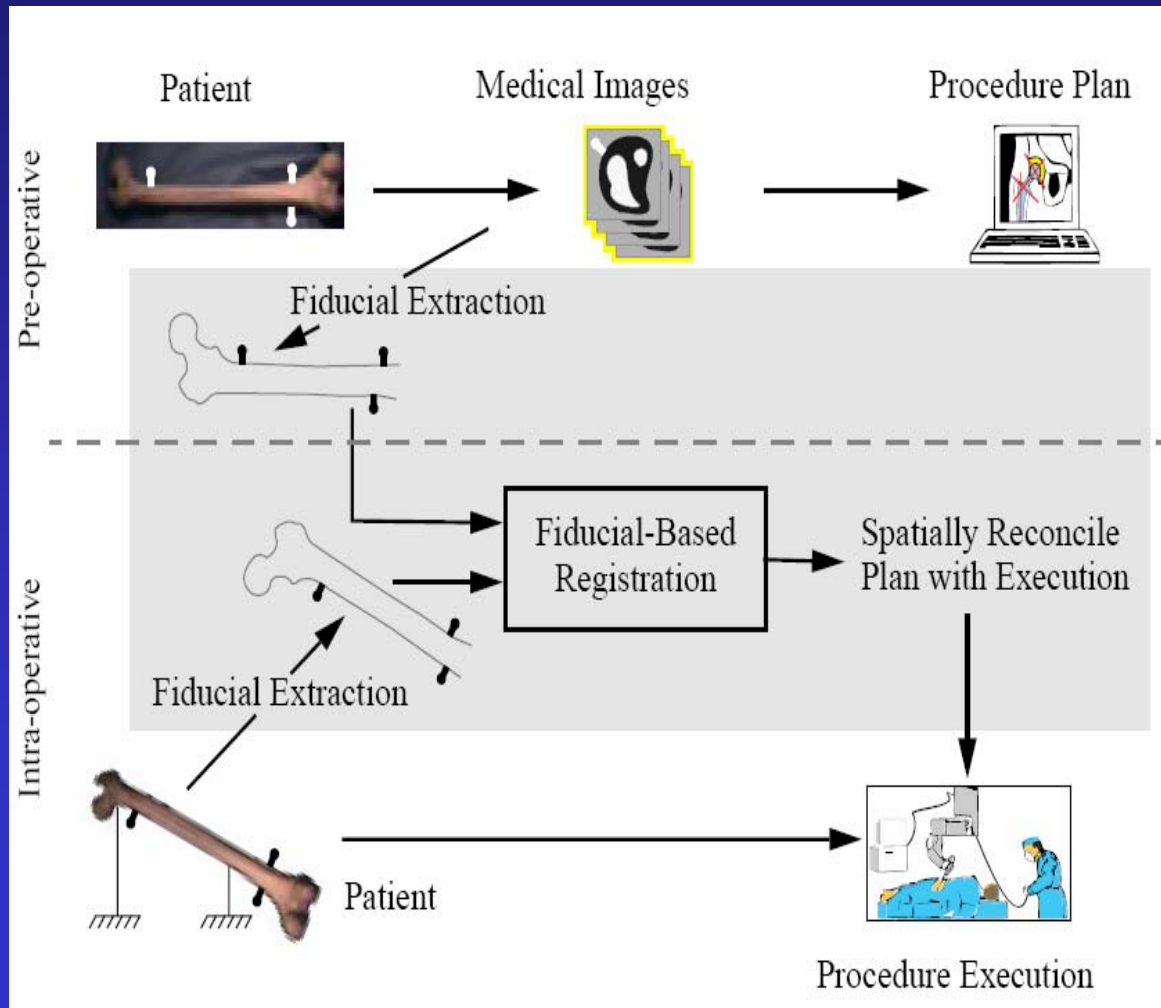
- Establish spatial relationship thus allowing 3D locations within pre-operative data to be unambiguously associated with the corresponding anatomical location on the actual patient in the operating room, and vice-versa
- Relate the measurement made in one coordinate system to those of another

# Instruments calibration



- Spatial transformation among tracking device, patient position and the image on the screen
- Enable image to show the patient from the surgeon's vantage

# Early approach : fiducial marker-based registration



- Intra-operatively, fiducial makers are physically exposed and tracked by intra-operative sensing device
- Given the 2 sets of the corresponding fiducial makers locations, spatial transformation is performed



# Pros and cons of fiducial marker-based registration

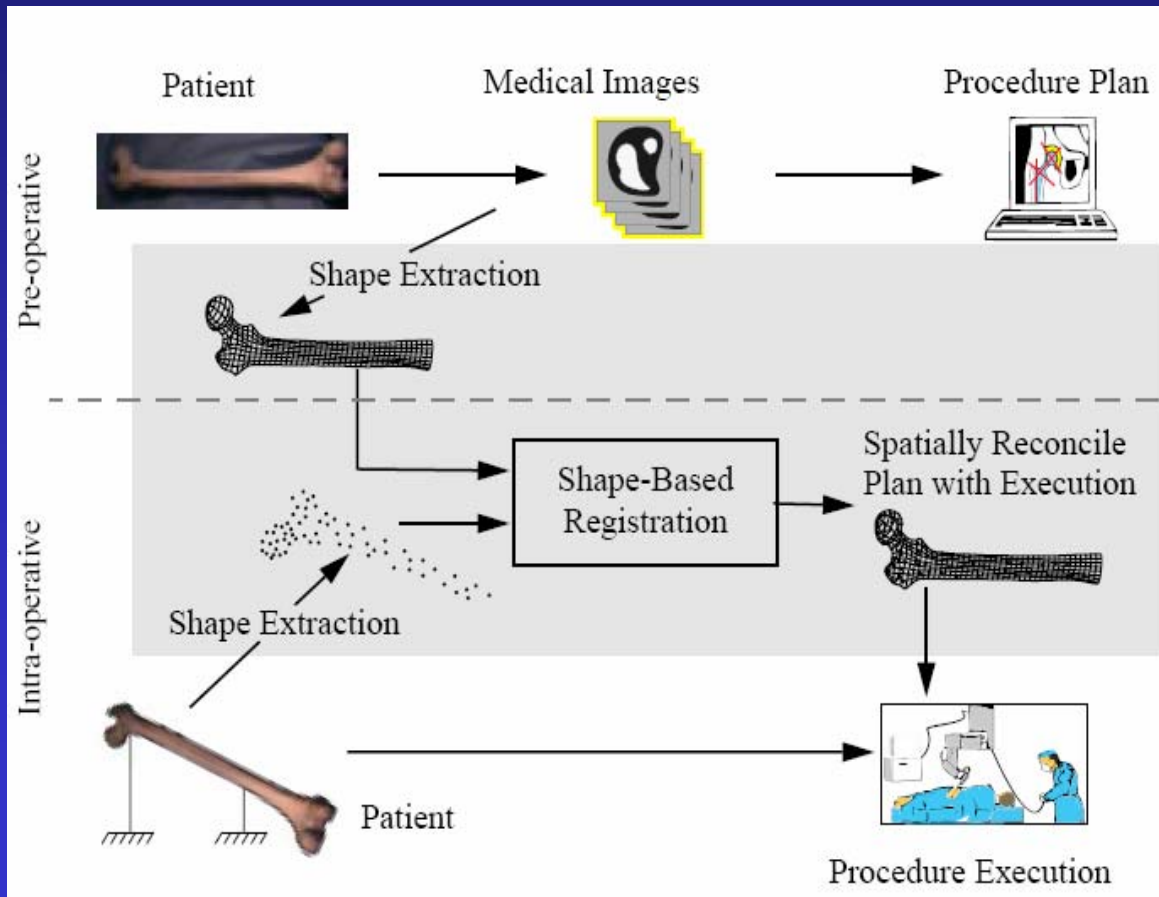
## Pros:

- Simple

## Cons:

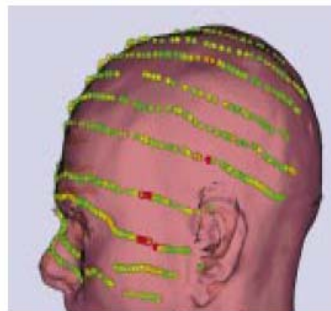
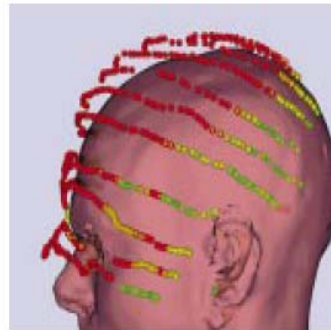
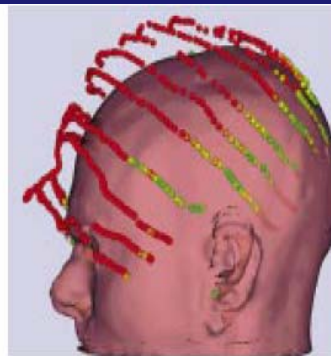
- Inconvenient, patients keep them attached between imaging and surgery
- Poor accuracy due to marker shifting
- Invasive if drill into the skull

# New approach: shape-based registration



- No fiducial markers needed
- Intra-operative shape extraction using laser scanning

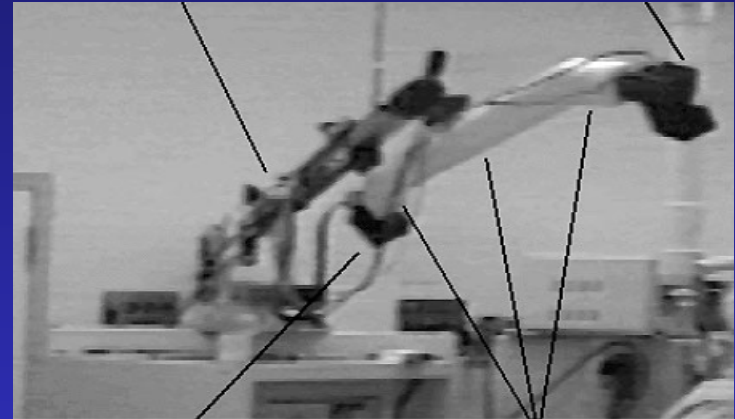
# Intra-operative laser scanning and registration



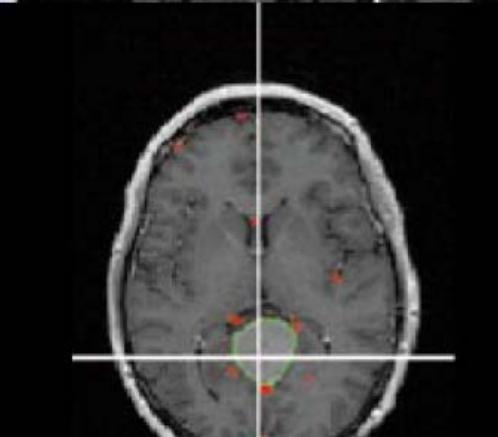
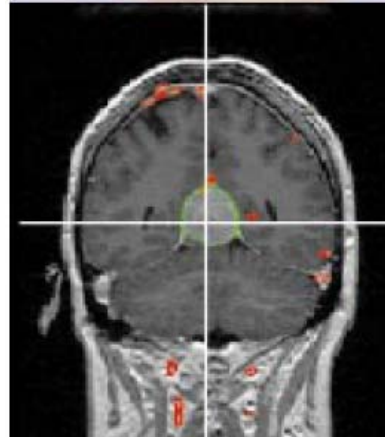
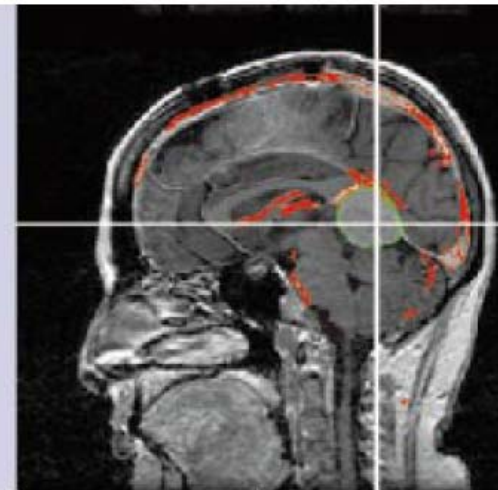
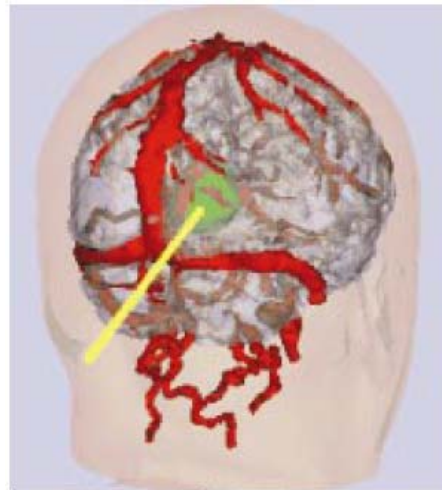
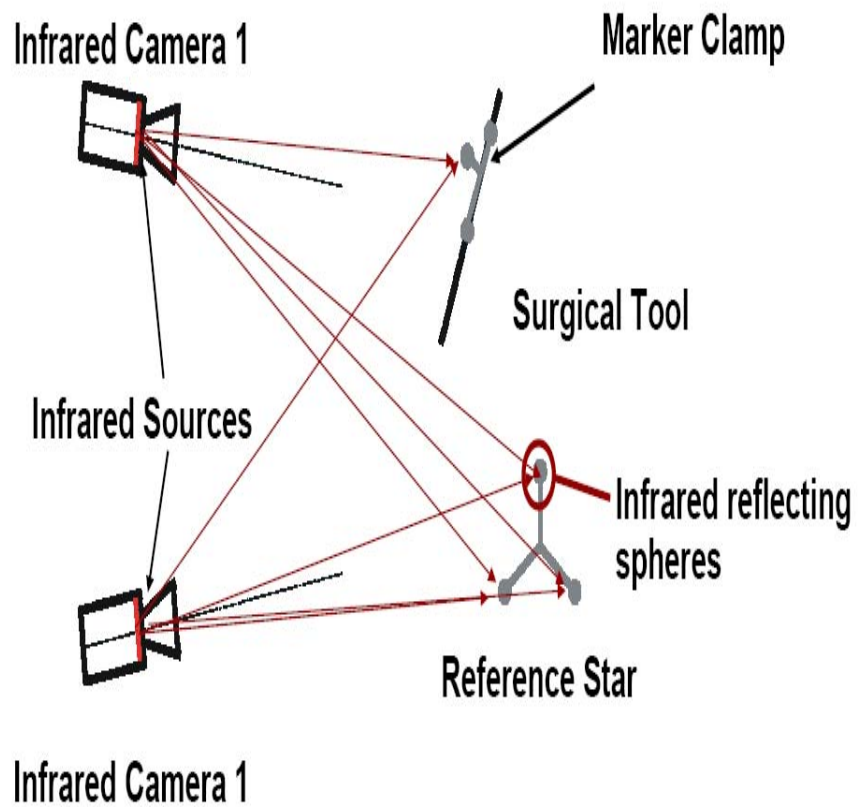
- With the laser 'cast' stored in the computer we rotate the virtual head till the face matches the contours of the laser lines

# Optical tracking system

- Instrument must be tracked and related to the patient image
- Accounts for motion of patient relative to camera system
- Use mounted flashing infrared LEDS
- Permits real time, dynamically referenced location of patient anatomy and surgical instrumentation



# Optical tracking system





# Surgical navigation

- Display method:
- Standard display plus video camera
- Head-mounted display

# Standard display on monitor

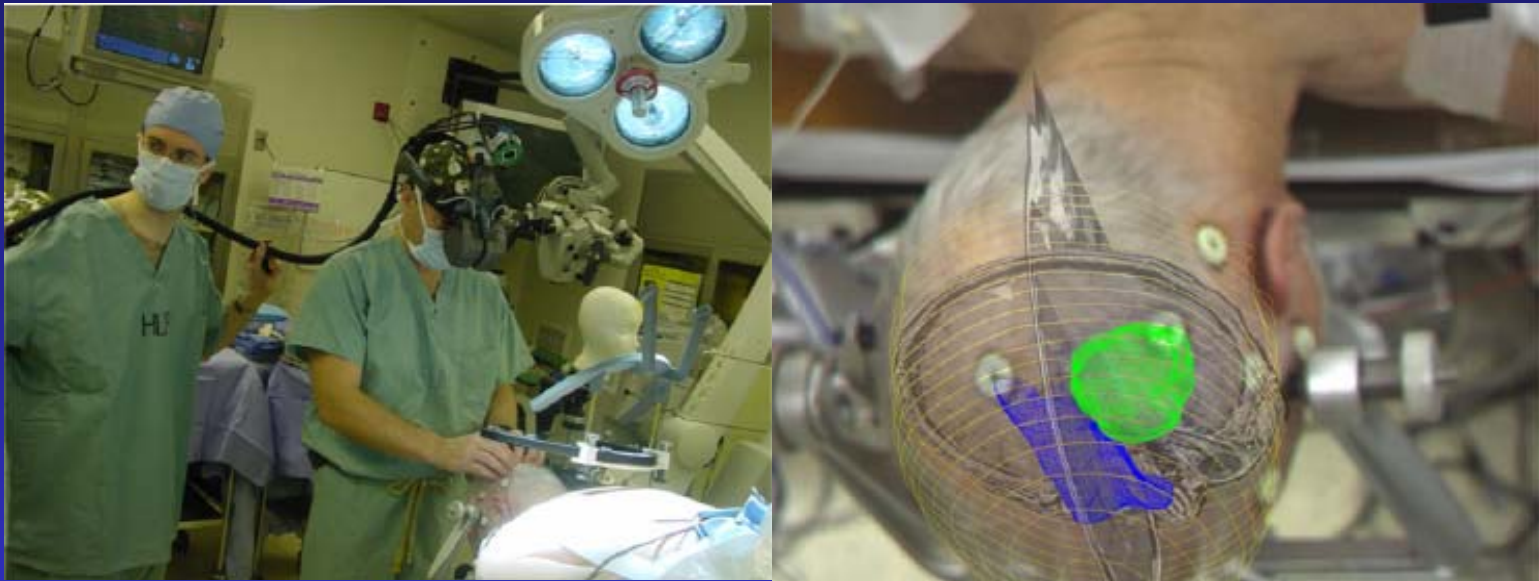


- Enhanced reality virtualization of internal structures blended with a video image
- The live video image is set up to duplicate the surgeon's point of view

# Drawbacks of display on monitor

- Doesn't appear directly in the environment of the patient
- Surgeon must look at the computer monitor while planning the approach
- Very sensitive to parallax

# Head-mounted display



- With the virtual image projected on to the patient
- Surgeon doesn't need to look at the monitor to experience the virtualization

# Drawbacks of Head-mounted display

- The head of the surgeon needs to be tracked and the virtual image on the display can be updated to eliminate the parallax
- Too cumbersome and bulky for surgery

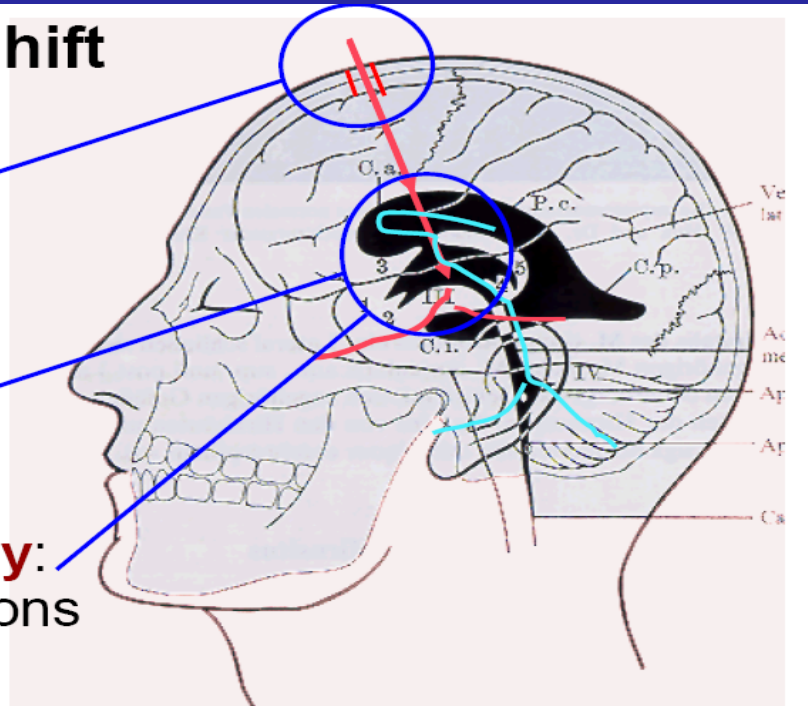


# Issue deformation

- IGS typically depends on pre-operative data acquisition
- Depending on target area, significant deformations may take place( e.g. brainshift )
- Data is not up-to-date, or intra-operative imaging is required

## Example for Brainshift

- **Drilled hole** in skull: significant deformations
- **Ventricular system**: negligible deformations
- After **ventriculostomy**: (still minor) deformations



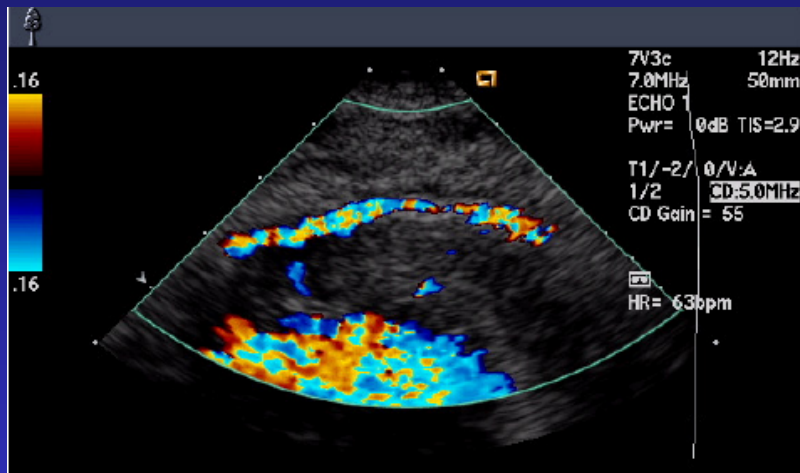
# Intra-operative imaging Open MRI approach



## Drawbacks:

- Limited access
- Low field scanner limited image quality
- Require MRI suitable instruments and OR

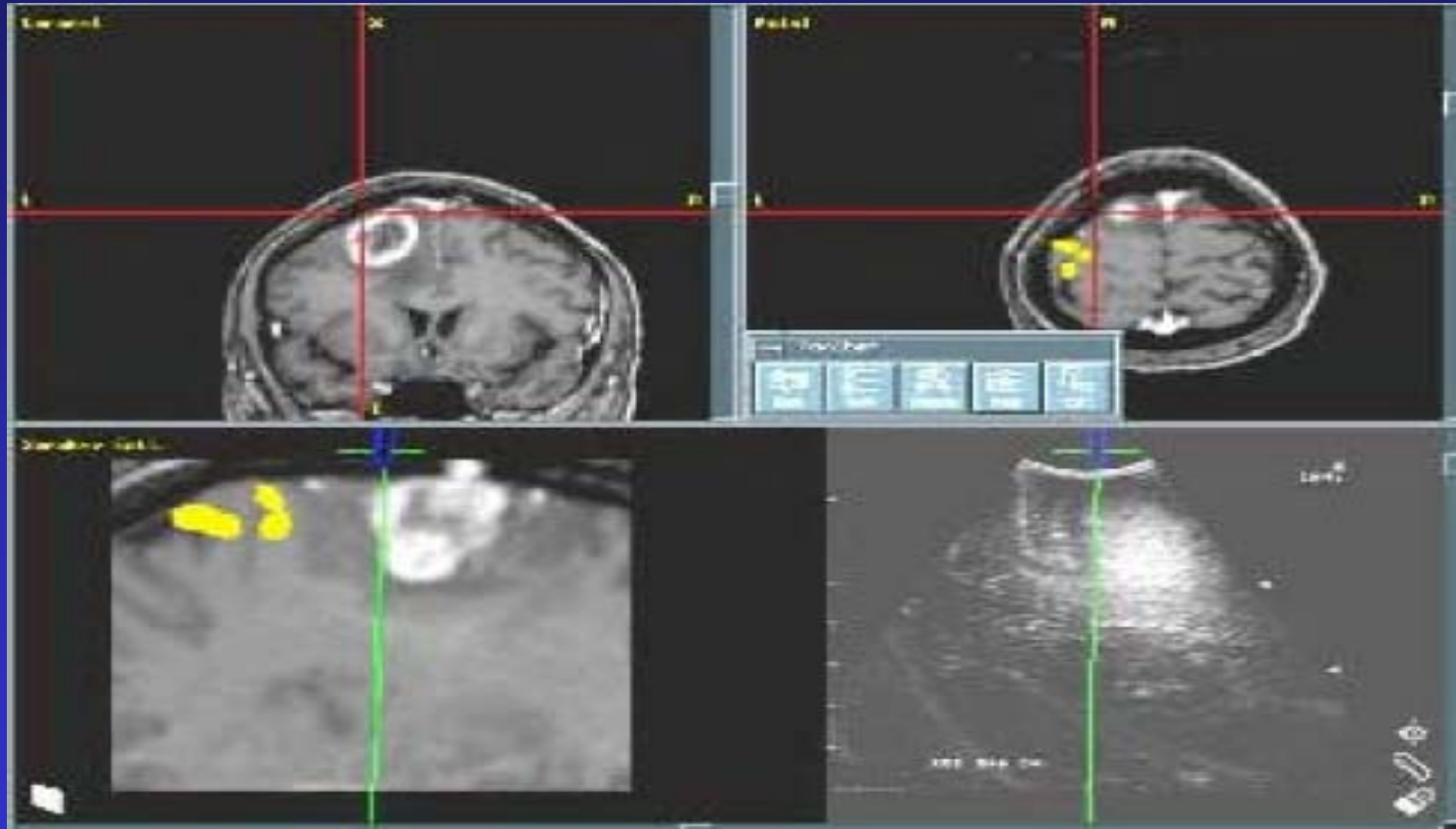
# Intra-operative imaging Ultrasound approach



- Emits sound waves and record echo
- Very noisy
- Low virtualization

# Intra-operative imaging

## Co-register approach



Ultrasound (low right) acquired during surgery co-registered with MRI (low left) to update the tumor position and surrounding anatomy

# IGS application

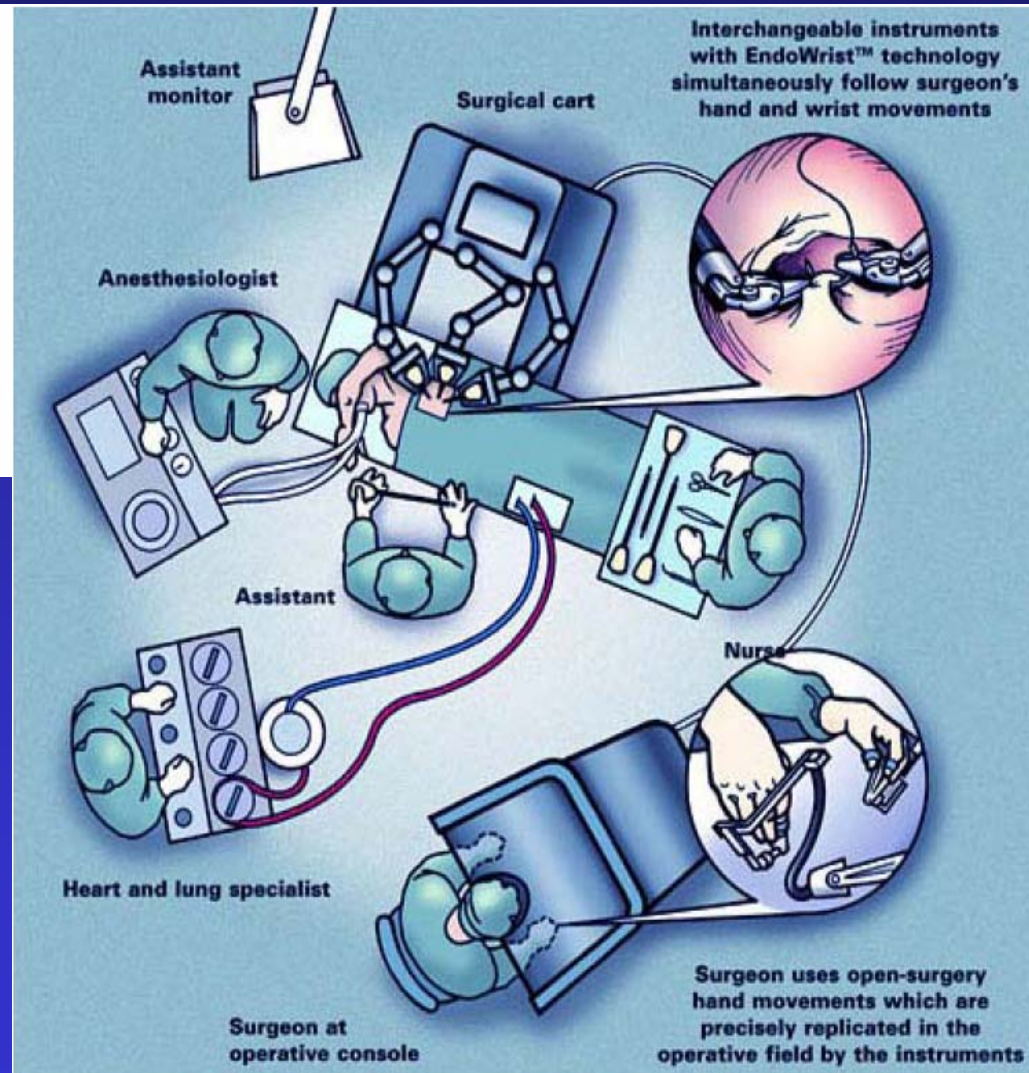
- Orthopaedics
- Neurosurgery
- Spine surgery
- Cranio-facial surgery



# Future: image-guided robotic surgery



- High precision
- No fatigue
- Increased dexterity
- Need intuitive surgeon-machine interface



# Summary

- IGS uses tracking and registration to match patient dataset to patient on OR table
- Minimum invasive surgery
- The IGS system must not add time and complication to the procedure
- User friendly system interface needed
- Next revolution: image-guided robotic surgery to enable the automation of surgical procedure

Thanks Everyone  
Any Questions?

# References

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