

# STABILITY

\* In most applications it is desirable that the circuit be "stable"

that is, for every bounded input signal, the output signal is also bounded.

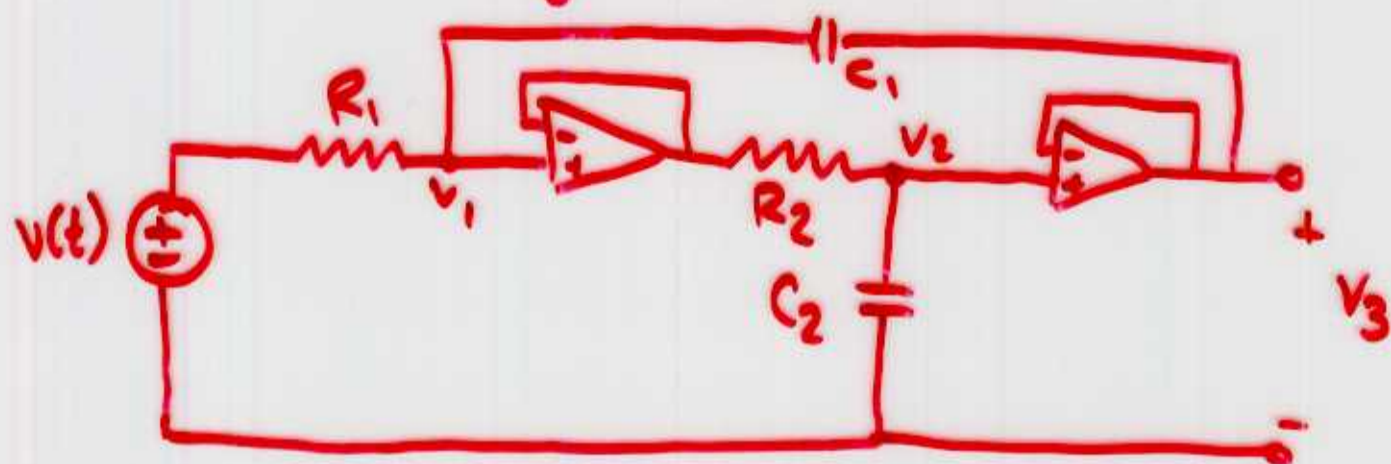
\* A nice property of the Laplace Transform is that it immediately tells us whether or not the circuit is stable, we don't have to go away and test every input signal!

## Theorem.

- 1) If the real part of <sup>each</sup> poles is negative, circuit is stable
- 2) If the real part of <sup>each</sup> ~~the~~ poles is positive, circuit is unstable
- 3) Poles on the "j $\omega$ " axis are sometimes said to be "quasi-stable" but can be considered unstable in practice

## EXAMPLE

Is the following circuit stable?



$$H(s) = \frac{V_3(s)}{V(s)} = \frac{\omega_0^2}{s^2 + \left(\frac{1}{R_1 C_1}\right)s + \omega_0^2}$$

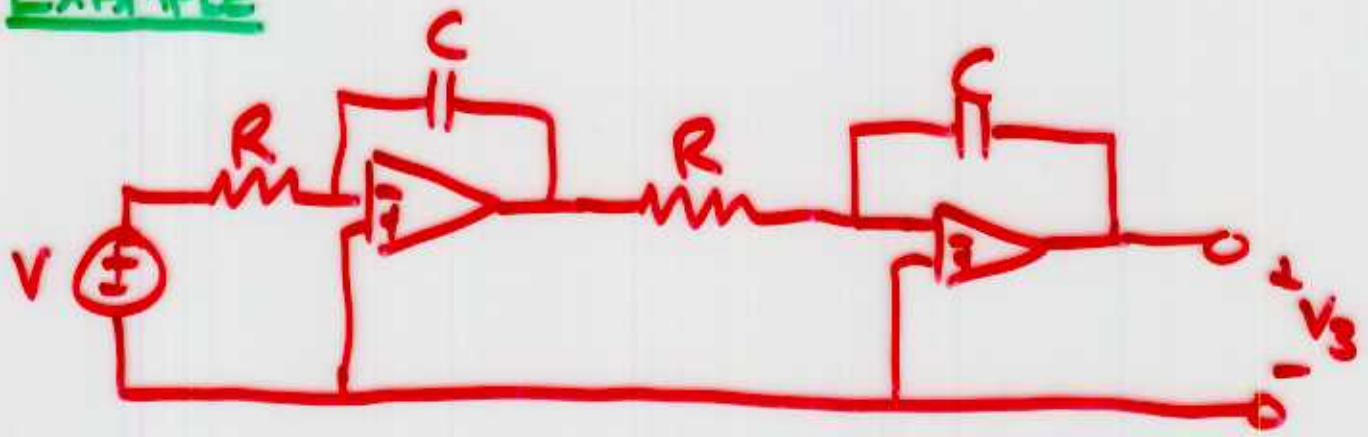
$$\text{where } \omega_0^2 = \frac{1}{R_1 R_2 C_1 C_2}$$

$$\text{Real part of roots} = \frac{-1}{2R_1 C_1}$$

which is always  $\leq 0$  for positive  $R_1, C_1$ .

Hence circuit is stable.

## EXAMPLE



$$H(s) = \frac{V_3(s)}{V(s)} = \frac{1}{(RC)^2 s^2}$$

$\Rightarrow$  two poles at origin

$\Rightarrow$  unstable

Example.

$$\text{step response} = \mathcal{L}^{-1} \left\{ \frac{H(s)}{s} \right\}$$

$$= \mathcal{L}^{-1} \left\{ \frac{1}{(RC)^2 s^3} \right\}$$

$$= \frac{1}{(RC)^2 3!} t^3$$

Note that this gets large as  $t \rightarrow \infty$

## IMPORTANT NOTE

Frequency response/phasor analysis only applies to stable circuits, but stability can only be determined from the Laplace Transform.