

COMP ENG 4TL4:

Digital Signal Processing

Notes for Lecture #7

Tuesday, September 23, 2003

Property: Suppose that for a given input $x[n]$ we have found *one particular* output sequence $y_P[n]$ so that a LCCD equation is satisfied. Then, the same equation with the same input is satisfied by any output of the form:

$$y[n] = y_P[n] + y_H[n],$$

where $y_H[n]$ is any solution to the LCCD equation with zero input, i.e., $x[n] = 0, \forall n \in [-\infty, \infty]$.

Remark: $y_P[n]$ and $y_H[n]$ are referred to as the particular and homogeneous solutions, respectively.

Proof: Taking the sum of:

$$\sum_{k=0}^N a[k] y_P[n-k] = \sum_{k=0}^M b[k] x[n-k]$$
$$\sum_{k=0}^N a[k] y_H[n-k] = 0 \quad \left(\Leftarrow \begin{array}{l} \text{homogeneous} \\ \text{equation} \end{array} \right)$$

we obtain:

$$\sum_{k=0}^N a[k] y[n-k] = \sum_{k=0}^M b[k] x[n-k],$$

with $y[n] = y_P[n] + y_H[n]$.

Property: An LCCD equation does not provide a unique specification of the output for a given input.

Corollary: Auxiliary information or conditions are required to specify uniquely the output for a given input.

Example: Let auxiliary information be in the form of N sequential output values (e.g, $\{y[-N], \dots, y[-2], y[-1]\}$).

Then:

- later values can be obtained by rearranging the LCCD equation as a *recursive* relation running forward in n , and
- prior values can be obtained by rearranging the LCCD equation as a *recursive* relation running backward in n .

LCCD equations as recursive procedures:

$$y[n] = \sum_{k=0}^M \frac{b[k]}{a[0]} x[n-k] - \sum_{k=1}^N \frac{a[k]}{a[0]} y[n-k] \quad \text{forwards}$$

$$y[n-N] = \sum_{k=0}^M \frac{b[k]}{a[N]} x[n-k] - \sum_{k=0}^{N-1} \frac{a[k]}{a[N]} y[n-k] \quad \text{backwards}$$

Example #1: First-order AR system $y[n] = ay[n-1] + x[n]$ with the given input $x[n] = b\delta[n-1]$ and the auxiliary condition $y[0] = y_0 \neq 0$.

Forwards recursion:

$$y[1] = ay_0 + b,$$

$$y[2] = ay[1] + 0$$

$$= a(ay_0 + b) = a^2y_0 + ab,$$

$$y[3] = a(a^2y_0 + ab) = a^3y_0 + a^2b,$$

... .. ,

$$y[n] = a^n y_0 + a^{n-1} b.$$

Note that:

$$y[n-1] = a^{-1}(y[n] - x[n]) \quad \Rightarrow$$

Backwards recursion:

$$y[-1] = a^{-1}(y_0 - 0)$$

$$= a^{-1}y_0,$$

$$y[-2] = a^{-2}y_0,$$

$$y[-3] = a^{-3}y_0,$$

$$\dots\dots\dots \dots \dots\dots,$$

$$y[-n] = a^{-n}y_0.$$

Question: Is this system LTI and causal?

Property: A linear system requires that the output be zero for all time when the input is zero for all time.

Proof: Represent zero input as a product of a zero constant $c = 0$ and an (arbitrary) non-zero signal $x[n]$:

$$c x [n] = 0 \cdot x [n] = 0.$$

Hence, for a linear system:

$$\begin{aligned} y [n] &= T \{c x [n]\} \\ &= c T \{x [n]\} \\ &= 0 \cdot T \{x [n]\} = 0. \end{aligned}$$

Example #1 (cont.): From the backwards recursion it follows that:

$$y[-n] = a^{-n}y_0 \neq 0 \quad \text{for} \quad a \neq 0, \quad y_0 \neq 0,$$

whereas $x[-n] = 0, n \geq 0 \Rightarrow$

According to the property proven on the previous slide, the system is nonlinear!

The system was implemented in both positive and *negative* directions beginning with $n = 0$

\Rightarrow the system is noncausal!

The forwards-backwards recursion can be rewritten for arbitrary n as:

$$y[n] = a^n y_0 + a^{n-1} b u[n-1].$$

Hence, a shift of the input by n_0 samples, $x_1[n] = x[n-n_0] = b\delta[n-n_0-1]$, gives:

$$\begin{aligned} y_1[n] &= a^n y_0 + a^{n-n_0-1} b u[n-n_0-1] \\ &\neq y[n-n_0] \quad \Rightarrow \end{aligned}$$

the system is not time-invariant!

Example #2: First-order AR system $y[n] = ay[n-1] + x[n]$ with the given input $x[n] = b\delta[n-1]$ and the auxiliary condition $y[0] = 0$.

Forwards-backwards recursion:

$$\begin{aligned} & \dots \dots \dots \dots \dots , \\ y[-1] &= 0, \\ y[0] &= 0, \\ y[1] &= a \cdot 0 + b \\ &= b, \\ y[2] &= ab, \\ & \dots \dots \dots \dots \dots , \\ y[n] &= a^{n-1}b. \end{aligned}$$

This recursion can be rewritten as:

$$y[n] = a^{n-1} b u[n-1], \quad \forall n.$$

It is easy to prove that this system is a causal LTI system.

⇒

For any system described by an LCCD equation:

- Linearity, time-invariance, and causality depend on auxiliary conditions!
- If an additional condition is that the system is initially at rest, then the system will be linear, time invariant, and causal.