Robust Coding Schemes for Distributed Sensor Networks with **Unreliable Sensors**

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Abstract — We consider a distributed sensor network in which several observations are communicated to the fusion center using limited transmission rate. The observations must be separately coded. We introduce a class of robust distributed coding schemes which flexibly trade off between system robustness and compression efficiency.

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I. INTRODUCTION

Consider the distributed sensor network shown in Fig. 1. $\{X(t)\}_{t=1}^{\infty}$ is the target data sequence which the fusion center tries to recover. This data sequence may not be observed directly. Corrupted versions of $\{X(t)\}_{t=1}^{\infty}$ are separately coded by 2 sensors. The data rate at which Sensor i (i = 1, 2) may transmit information about its observations is limited to R_i bits per second. The sensors are not permitted to communicate with each other; i.e., Sensor i has to send data based solely on its own noisy observations $\{Y_i(t)\}_{t=1}^{\infty}$.

$$\begin{array}{c|c} X(t) & \overbrace{\text{Obser-}} & Y_1(t) & \overbrace{\text{Sensor 1: } f_{E,1}^{(n)}(y_1^n)} & C_1^{(n)} \\ \hline & Y_2(t) & \overbrace{\text{Sensor 2: } f_{E,2}^{(n)}(y_2^n)} & C_2^{(n)} & \overbrace{\text{Center}} & \hat{X}(t) \\ \hline & p(y_1, y_2|x) & \end{array}$$

Figure 1: Model of distributed sensor network with unreliable sensors

Let $\{X(t), Y_1(t), Y_2(t)\}_{t=1}^{\infty}$ be temporally memoryless source with instantaneous joint probability distribution $P(x, y_1, y_2)$ on $\mathcal{X} \times \mathcal{Y}_1 \times \mathcal{Y}_2$, where \mathcal{X} is the common alphabet of the random variables X(t) for $t = 1, 2, \dots, \mathcal{Y}_i$ (i = 1, 2)is the common alphabet of the random variables $Y_i(t)$ for $t = 1, 2, \cdots$. If Sensor *i* is able to function, then it encodes a block $y_i^n = [y_i(1), \cdots, y_i(n)]$ of length n from its observed data using a source code $c_i^{(n)} = f_{E,i}^{(n)}(y_i^n)$ of rate $\frac{1}{n} \log |\mathcal{C}_i^{(n)}|$. If the fusion center only receives the data from Sensor i, then it tries to recover the target sequence $x^n = [x(1), \dots, x(n)]$ by implementing a mapping $f_{D,i}: \mathcal{C}_i \to \mathcal{X}^n$ (i = 1, 2). If the fusion center receives the data from both sensors, then it tries to recover the target sequence by implementing a mapping $f_{D,3}: \mathcal{C}_1^{(n)} \times \mathcal{C}_2^{(n)} \to \mathcal{X}^n.$

This model subsumes the multiple description problem [1] and the CEO problem [2], and was first studied in [3].

Definition 1 The quintuple $(R_1, R_2, D_1, D_2, D_3)$ is called achievable, if $\forall \varepsilon > 0$, $\exists n_0$ such that $\forall n > n_0$ there exist encoding functions:

$$f_{E,i}^{(n)}: \mathcal{Y}_i^{(n)} \to \mathcal{C}_i^{(n)} \quad \log |\mathcal{C}_i^{(n)}| \le n(R_i + \varepsilon) \quad i = 1, 2$$

and decoding functions:

$$f_{D,i}: \ C_i^{(n)} \to \mathcal{X}^n \quad i = 1,2$$

$$f_{D,3}: \ C_1^{(n)} \times C_2^{(n)} \to \mathcal{X}^n$$
such that for $\hat{X}_i^n = f_{D,i}(f_{E,i}(Y_i^n))$ $(i = 1,2)$, and for $\hat{X}_3^n = f_{D,3}(f_{E,1}(Y_i^n), f_{E,1}(Y_i^n))$,

$$\frac{1}{n}E\sum_{t=1}^{n} d(X(t), \hat{X}_{i}(t)) < D_{i} + \varepsilon \quad i = 1, 2, 3.$$

Here $d(\cdot, \cdot) : \mathcal{X} \times \mathcal{X} \to [0, d_{max}]$ is a given distortion measure. Let \mathcal{Q} denote the set of all achievable quintuples.

II. MAIN RESULTS

Theorem 1 $(R_1, R_2, D_1, D_2, D_3)$ is achievable, if there exist random variables $(W_{1,1}, W_{1,2}, W_{2,1}, W_{2,2})$ jointly distributed with the generic source variables (X, Y_1, Y_2) such that the following properties are satisfied:

(i)
$$(W_{1,1}, W_{1,2}) \to Y_1 \to (X, Y_2, W_{2,1}, W_{2,2}),$$

 $(W_{2,1}, W_{2,2}) \to Y_2 \to (X, Y_1, W_{1,1}, W_{1,2});$
(ii)

$$\begin{aligned} R_1 &\geq I(Y_1; W_{1,1}) + I(Y_1; W_{1,2} | W_{1,1}, W_{2,1}, W_{2,2}) \\ R_2 &\geq I(Y_2; W_{2,1}) + I(Y_2; W_{2,2} | W_{1,1}, W_{2,1}, W_{1,2}) \\ R_1 + R_2 &\geq I(Y_1; W_{1,1}) + I(Y_2; W_{2,1}) \\ &+ I(Y_1, Y_2; W_{1,2}, W_{2,2} | W_{1,1}, W_{2,1}); \end{aligned}$$

(iii) There exist functions:

$$f_i: \mathcal{W}_{i,1} \to \mathcal{X} \quad i = 1, 2,$$

$$f_3: \mathcal{W}_{1,1} \times \mathcal{W}_{1,2} \times \mathcal{W}_{2,1} \times \mathcal{W}_{2,2} \to \mathcal{X},$$

such that
$$Ed(X, \hat{X}_i) \leq D_i$$
 $(i = 1, 2, 3)$, where $\hat{X}_1 = f_1(W_{1,1}), \quad \hat{X}_2 = f_2(W_{2,1})$ and $\hat{X}_3 = f_3(W_{1,1}, W_{1,2}, W_{2,1}, W_{2,2}).$

If \mathcal{C} denotes the set of these achievable quintuples, then time sharing yields that $conv(\mathcal{C})$ is also an achievable region.

References

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