

1. Suppose an ac source is connected to a capacitor through conductors. Explain the meaning of the conduction current in the conductor and the meaning of the displacement current between the capacitor plates, which is filled with a dielectric material. Can there be displacement current in the conductor? Provide explanation.

5 marks

The conduction current is the current due to moving charges, $I = \frac{dQ}{dt}$. The displacement current is an “equivalent” current that is related to the rate of change of electric flux, i.e., $I_d = \frac{d\Phi_E}{dt}$.

From one of Maxwell's equations, we have

$$\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t},$$

where the first term on the right hand side is the conduction current density and the second term is the displacement current density.

$$\int (\nabla \times \vec{H}) \cdot d\vec{s} = \int \vec{J} \cdot d\vec{s} + \int \left(\frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{s}$$

Applying Stokes Theorem

$$\int_s (\nabla \times \vec{H}) \cdot d\vec{s} = \oint_L \vec{H} \cdot d\vec{l} = I + I_d$$

Where

$$I = \int \vec{J} \cdot d\vec{s} \text{ is the conduction current and}$$

$$I_d = \int \left(\frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{s} \text{ is the displacement current}$$

Between the capacitor plates, there is no conduction current if the plates are separated by a perfect insulator. This is because there are no free charge carriers in a perfect insulator. Practically the real insulator consists of a very few charge carriers and therefore a very small leakage current passes in the capacitor depending on the conductivity of the insulator.

When a time varying voltage (AC) is applied on the capacitor, there exists a displacement current between the capacitor plates since the electric flux density changes as a function of time. The electric flux density, $\vec{D} = \epsilon \vec{E}$ where epsilon is the dielectric constant and E is the electric field intensity. If the applied voltage varies sinusoidally with time, electric field intensity E (which is proportional to V) also varies sinusoidally with time, leading to time-changing D.

Since the electric field intensity changes with time in the conductor as well, there is a small displacement current in the conductor, too. However, the magnitude of the displacement current is much smaller than the conduction current.

2

$$\nabla \times \underline{E} = -\frac{\partial \underline{B}}{\partial t} = -\mu \frac{\partial \underline{H}}{\partial t} \rightarrow (1) \quad , \text{ as } \underline{B} = \mu \underline{H}$$

$$\nabla \times \underline{H} = \underline{J} + \frac{\partial \underline{D}}{\partial t} = \sigma \underline{E} + \epsilon \frac{\partial \underline{E}}{\partial t} \rightarrow (2) \quad , \text{ as } \underline{J} = \sigma \underline{E} \text{ , } \underline{D} = \epsilon \underline{E}$$

Since, $\underline{E} = E_x \hat{x}$, $\underline{H} = H_y \hat{y}$

subst. in RHS of (1) :-

$$-\mu \frac{\partial H_y}{\partial t} \hat{y} = -\mu \frac{\partial H_y}{\partial t} \hat{y}$$

So, we need, only, y-component of LHS of (1) :-

$$(\nabla \times \underline{E})_y = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & 0 & 0 \end{vmatrix} = \frac{\partial E_x}{\partial z} \hat{y}$$

$$\therefore \frac{\partial E_x}{\partial z} = -\mu \frac{\partial H_y}{\partial t} \rightarrow (3)$$

subst. in RHS of (2) :-

$$\sigma E_x \hat{x} + \epsilon \frac{\partial E_x}{\partial t} \hat{x}$$

So, we need x-component of LHS of (2) :-

$$(\nabla \times \underline{H})_x = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & H_y & 0 \end{vmatrix} = -\frac{\partial H_y}{\partial z} \hat{x}$$

$$\therefore -\frac{\partial H_y}{\partial z} = \sigma E_x + \epsilon \frac{\partial E_x}{\partial t} \rightarrow (4)$$

Assume, $E_x = \text{Re}\{E_{xs} e^{j\omega t}\}$, $H_y = \text{Re}\{H_{ys} e^{j\omega t}\}$

subst. in (3) & (4) :-

$$\frac{\partial E_{xs}}{\partial z} = -j\omega\mu H_{ys} \rightarrow (5)$$

$$-\frac{\partial H_{ys}}{\partial z} = \sigma E_{xs} + j\omega\epsilon E_{xs} \rightarrow (6)$$

diff. (5) w.r.t. z :-

$$\frac{\partial^2 E_{xs}}{\partial z^2} = -j\omega\mu \frac{\partial H_{ys}}{\partial z} \rightarrow (7)$$

Subst. from (6) in (7) :-

$$\frac{\partial^2 E_{xs}}{\partial z^2} = j\omega\mu (\sigma E_{xs} + j\omega\epsilon E_{xs})$$

$$\therefore \frac{\partial^2 E_{xs}}{\partial z^2} = j\omega\mu (\sigma + j\omega\epsilon) E_{xs} \quad \#$$

(a) 3'

$$\mathbf{H} = \frac{\mathbf{B}}{\mu} = \frac{B_x}{\mu} \vec{\mathbf{x}} = \frac{3 \times 10^{-4} \cos 10^5 t \sin 10^{-3} y}{10^{-5}} \vec{\mathbf{x}} = 30 \cos 10^5 t \sin 10^{-3} y \vec{\mathbf{x}} \frac{A}{m} \quad (0.5')$$

$$\nabla \times \mathbf{H} = -\hat{\mathbf{z}} \frac{\partial H_x}{\partial y} = -0.03 \cos 10^5 t \cos 10^{-3} y \hat{\mathbf{z}} \frac{A}{m^2} \quad (0.5')$$

$$\frac{d\mathbf{E}}{dt} = \frac{\nabla \times \mathbf{H}}{\varepsilon} = \frac{-0.03 \cos 10^5 t \cos 10^{-3} y \hat{\mathbf{z}}}{2 \times 10^{-11}} = -1.5 \times 10^9 \cos 10^5 t \cos 10^{-3} y \hat{\mathbf{z}} \frac{V}{ms} \quad (0.5')$$

$$\mathbf{E} = \int \frac{d\mathbf{E}}{dt} dt = -1.5 \times 10^4 \sin 10^5 t \cos 10^{-3} y \hat{\mathbf{z}} \frac{V}{m} \quad (0.5')$$

Direction: 0.5, Unit: 0.5

(b) 2'

$$\Phi = \iint \mathbf{B} d\mathbf{S} = \iint B_x dy dz = \int_0^5 dz \int_0^{30} 3 \times 10^{-4} \cos 10^5 t \sin 10^{-3} y dy = 1.5 \cos 10^5 t (1 - \cos 0.03)$$

(0.5')

$$= 1.5 \cos 0.1 (1 - \cos 0.03) \quad (0.5')$$

$$= 6.72 \times 10^{-4} \text{Wb} \quad (0.5')$$

Unit 0.5'.