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EXAMPLE: SINUSOIDAL WAVE WITH RANDOM PHASE

CONSIDER THE RANDOM PROCESS DEFINED BY

$$X(t) = A \cos(2\pi f_c t + \Theta) \rightarrow (25)$$

WHERE  $A$  &  $f_c$  ARE CONSTANTS.  $\Theta$  IS A RANDOM VARIABLE AND ITS ~~PHASE~~ CAN TAKE ANY VALUE BETWEEN  $0$  &  $2\pi$  WITH EQUAL PROBABILITY, I.E. ITS pdf IS ~~UNIFORM~~ GIVEN BY

$$f(\theta) = \begin{cases} \frac{1}{2\pi} & 0 \leq \theta < 2\pi \\ 0 & \text{ELSEWHERE} \end{cases} \rightarrow (26)$$

FIND THE MEAN, <sup>VARIANCE</sup> AND AUTO-CORRELATION.

THE MEAN IS GIVEN BY

$$E[X(t)] = E[A \cos(2\pi f_c t + \Theta)]$$

$$= A \cos(2\pi f_c t) E[\cos \Theta]$$

$$= E[A \cos(2\pi f_c t) \cos \Theta - A \sin(2\pi f_c t) \sin \Theta]$$

$$= A \cos(2\pi f_c t) E[\cos \Theta] - A \sin(2\pi f_c t) E[\sin \Theta]$$

$\rightarrow (27)$

BY DEFINITION,

$$E[\cos(\theta)] = \int_{-\infty}^{\infty} \cos(\theta) f(\theta) d\theta = \int_{-\infty}^{\infty} f(\theta) \cos \theta d\theta$$

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$$\text{i.e. } E[\cos \theta] = \frac{1}{2\pi} \int_0^{2\pi} \cos \theta \, d\theta = 0 \rightarrow (28)$$

$$\text{SIMILARLY } E[\sin \theta] = 0 \rightarrow (29)$$

USING (28) & (29) IN (27), WE FIND THAT

$$E[X(t)] = 0 \rightarrow (30)$$

SINCE THE MEAN IS ZERO, VARIANCE IS SIMPLY THE SECOND MOMENT, I.E.

$$\sigma_x^2 = E[X^2(t)] = E[A^2 \cos^2(2\pi f_c t + \theta)]$$

$$= E\left\{ \frac{A^2}{2} [1 + \cos(4\pi f_c t + 2\theta)] \right\}$$

$$= \frac{A^2}{2} + \frac{A^2}{2} E[\cos(4\pi f_c t + 2\theta)]$$

$$= \frac{A^2}{2} + \frac{A^2}{2} E[\cos(4\pi f_c t) \cos(2\theta) - \sin(4\pi f_c t) \sin(2\theta)]$$

$$= \frac{A^2}{2}$$

SINCE  $E(\cos 2\theta)$  &  $E(\sin 2\theta)$  ARE

ZEROS SIMILAR TO EQ. (28) & (29) ..

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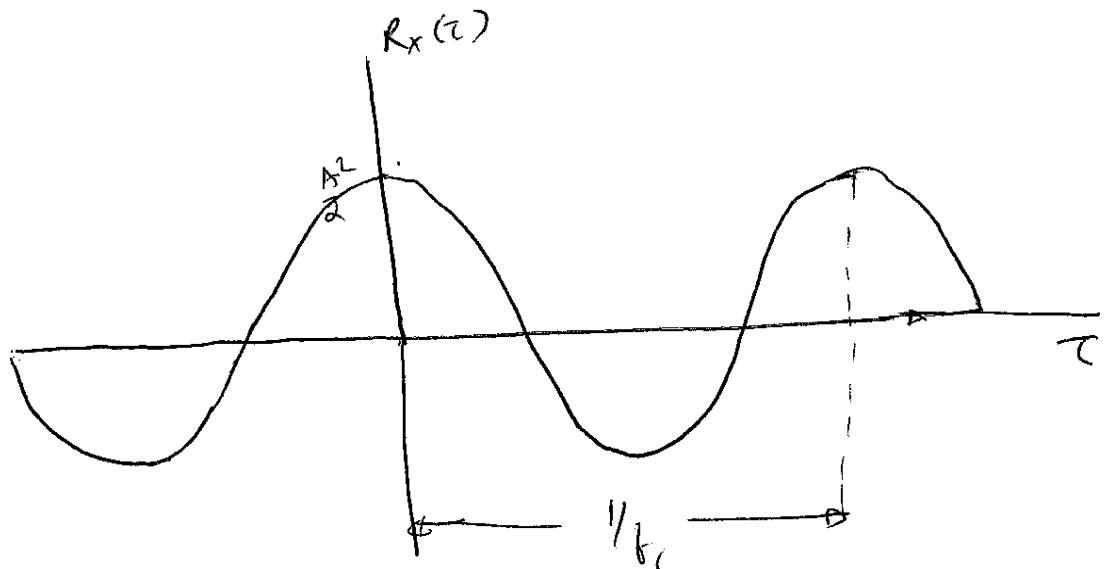
THE AUTO-CORRELATION FUNCTION OF  $X(t)$  IS

$$\begin{aligned}
 R_X(\tau) &= E[X(t+\tau)X(t)] \\
 &= E\left\{\cos[2\pi f_c(t+\tau) + \theta] \cdot \cos[2\pi f_c t + \theta]\right\} \cdot A^2 \\
 &= \frac{A^2}{2} E\left\{\cos[4\pi f_c t + 2\pi f_c \tau + 2\theta] + \cos[2\pi f_c \tau]\right\} \\
 &= \frac{A^2}{2} \left\{E[\cos(\alpha + 2\theta)] + E[\cos(2\pi f_c \tau)]\right\}
 \end{aligned}$$

WHERE  $\alpha = 4\pi f_c t + 2\pi f_c \tau$ ;

WHENEVER  $E[\cos(\alpha + 2\theta)] = E[\cos \alpha \cdot \cos(2\theta) - \sin \alpha \cdot \sin(2\theta)]$   
 $= 0$

$\therefore R_X(\tau) = \frac{A^2}{2} \cos(2\pi f_c \tau)$  ( $\because \cos(2\pi f_c \tau)$  IS DETERMINISTIC)



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## FREQ. DOMAIN REPRESENTATION OF NOISE

WHEN A SIGNAL CORRUPTED BY NOISE PASSES THROUGH A FILTER, FREQUENCY COMPONENTS OF THE INPUT SIGNAL (i.e. SIGNAL + NOISE) IS ALTERED BY THE FILTER. TO UNDERSTAND THE IMPACT OF FILTER, IT IS NECESSARY TO KNOW THE SPECTRAL CHARACTERISTICS OF THE NOISE. FOR EXAMPLE, WE LIKE TO KNOW WHAT HAPPENS WHEN A RANDOM PROCESS WITH MEAN  $m_x$  PASSES THROUGH A FILTER. SINCE THE MEAN  $m_x$  IS CONSTANT FOR A STATIONARY RANDOM PROCESS, ITS FOURIER TRANSFORM IS A DELTA FUNCTION, i.e.,

$$F\{E\{x(t)\}\} = F[m_x] = m_x \cdot \delta(f)$$

THE MEAN OF THE INPUT SIGNAL IS MULTIPLIED BY THE FILTER TRANSFER FUNCTION  $H(f)$  AT  $f=0$ , i.e., THE MEAN OF THE OUTPUT SIGNAL,  $y(t)$  IS GIVEN BY

$$m_y = m_x \cdot H(0)$$

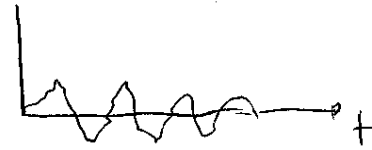
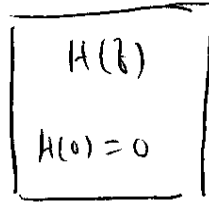
→ (31)

FOR EXAMPLE, IF THE INPUT <sup>RANDOM</sup> SIGNAL PASSES THROUGH A CAPACITOR, THE D.C. COMPONENT IS BLOCKED AND THEREFORE, THE MEAN OF THE OUTPUT RANDOM PROCESS  $y(t)$  IS ZERO, AS SHOWN IN THE FIGURE.



SYSTEM

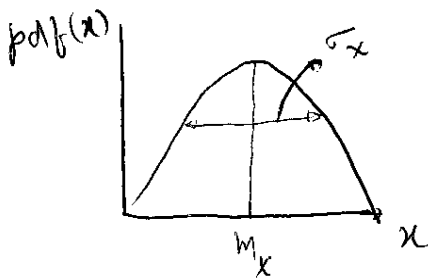
$m_y = 0$



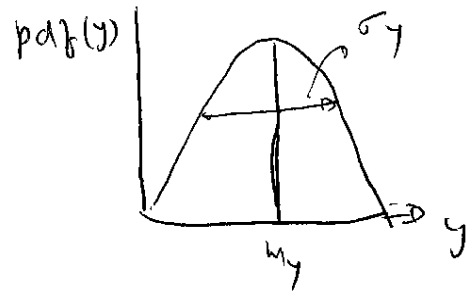
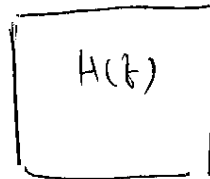
INPUT RANDOM PROCESS,  $X(t)$

OUTPUT RANDOM PROCESS,  $Y(t)$

SUPPOSE THE VARIANCE OF THE INPUT RANDOM PROCESS IS  $\sigma_x^2$ .  
 WHAT WOULD BE THE OUTPUT VARIANCE OF THE OUTPUT RANDOM PROCESS ?



SYSTEM



INPUT RANDOM PROCESS  $X(t)$

$m_y = m_x \cdot H(0)$

$\sigma_y = ?$

SINCE VARIANCE IS A SPECIAL CASE OF AUTO-CORRELATION WITH A TIME SHIFT OF ZERO, WE CAN AS WELL INVESTIGATE THE FREQ. DOMAIN REPRESENTATION OF AUTO-CORRELATION FUNCTION GIVEN BY,

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$$R_x(t) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T x(\tau) x(\tau+t) d\tau \quad \rightarrow (32)$$

INSTEAD OF THE MEASUREMENT INTERVAL  $[0, T]$ , WE CHOOSE A SYMMETRIC INTERVAL  $[-T/2, T/2]$ . THE VALUE OF THE CORRELATION FUNCTION IS UNCHANGED BY THIS SHIFT.

$$R_x(t) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(\tau) x(\tau+t) d\tau \quad \rightarrow (33)$$

SINCE  $R_x(t)$  IS SYMMETRIC,  $R_x(t) = R_x(-t)$ , EQ. (33) MAY BE REWRITTEN AS

$$R_x(t) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(\tau) x(\tau-t) d\tau \quad \rightarrow (34)$$

EQ. (34) LOOKS SIMILAR TO CONVOLUTION OF  $x(t)$  WITH ITSELF. BUT IN THE CASE OF CONVOLUTION, ONE OF THE SIGNALS IS INVERTED BEFORE THE TIME SHIFT, I.E.

$$x_1(t) * x_2(t) = \int_{-\infty}^{\infty} x_1(\tau) x_2(t-\tau) d\tau \quad \rightarrow (35)$$

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IN Eq. (35), IF WE CHOOSE  $x_1(t) = x(t)$  &  ~~$x_2(t) = x(t)$~~

$x_2(t) = x(-t)$ ,  $x_2(t-\tau)$  ON THE RHS BECOMES  ~~$x_2(t)$~~

$x(t-\tau)$ , i.e.,

~~$$R_x(t) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T}^T x(t) * x(-t) dt$$~~

$$R_x(t) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T}^T x(\tau) x(\tau-t) d\tau \rightarrow (36)$$

THE RHS OF EQ. (36) IS THE SAME AS THAT OF EQ. (35). THE INTEGRAL OF

SO, WE WRITE

$$R_x(t) = \lim_{T \rightarrow \infty} \frac{1}{T} [x(t) * x(-t)] \rightarrow (37)$$

USING THE CONVOLUTION THEOREM, CONVOLUTION IN TIME

DOMAIN MAY BE WRITTEN AS MULTIPLICATION IN

FREQUENCY DOMAIN, i.e.

$$F[R_x(t)] = \lim_{T \rightarrow \infty} \frac{1}{T} X(f) \cdot F[x(-t)] \rightarrow (38)$$

WHERE  $X(f) = F[x(t)]$ .

SINCE  $F[x(-t)] = X^*(f)$ , IT FOLLOWS THAT

$$F[R_X(t)] = \lim_{T \rightarrow \infty} \frac{1}{T} |X(f)|^2 \rightarrow (39)$$

THE QUANTITY ON THE RHS OF EQ. (39) IS CALLED THE POWER SPECTRAL DENSITY (PSD). THEREFORE, PSD AND AUTO-CORRELATION FUNCTION ARE FOURIER TRANSFORM PAIRS.

$$PSD = \lim_{T \rightarrow \infty} \frac{1}{T} |X(f)|^2 \rightarrow (40)$$

$$R_X(t) \xLeftrightarrow{\quad} PSD(f) \rightarrow (41)$$

† IF  $x(t) \xLeftrightarrow{\quad} X(f)$ , THEN CONSIDER

$$F[x(-t)] = \int_{-\infty}^{\infty} x(-t) e^{-j2\pi f t} dt$$

$$\text{LET } t = -u, \quad \frac{dt}{du} = -1, \quad F[x(-t)] = \int_{-\infty}^{\infty} x(u) e^{j2\pi f u} du = X(-f)$$

FOR REAL SIGNALS, WE HAVE  $X(-f) = X^*(f)$