

- Note that since  $X(s) \rightarrow \infty$  as  $s \rightarrow a$  pole,  
the ROC cannot contain any poles
- We will see that the poles define the boundaries  
of the ROC.
- The ROC is required in order to invert the Laplace  
Transform

### EXAMPLE 6

$$x(t) = e^{at} u(t),$$

$$\Rightarrow X(s) = \int_{-\infty}^{\infty} e^{at} u(t) e^{-st} dt$$

$$= \int_0^{\infty} e^{(s-a)t} dt$$

$$= \frac{1}{s-a} [e^{(s-a)t}]_0^{\infty}$$

$$\Rightarrow X(s) = \frac{1}{s-a} e^{-(s-a)t} e^{-j\omega t} \Big|_0^{\infty}$$

If  $\sigma > a$   $e^{(\sigma-a)t} \rightarrow 0$  as  $t \rightarrow \infty$

$$\Rightarrow X(s) = \frac{1}{s-a}, \operatorname{Re}(s) > a$$

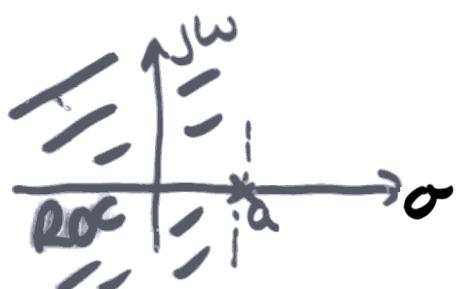
The Laplace Transform does not exist for  $\sigma \leq a$



## EXAMPLE 6.2

$$y(t) = -e^{-at} u(-t)$$

$$\begin{aligned} Y(s) &= \int_{-\infty}^{\infty} e^{-at} u(-t) e^{st} dt \\ &= \int_{-\infty}^0 e^{(s-a)t} e^{-j\omega t} dt \\ &= \left[ \frac{1}{s-a} e^{-(s-a)t} e^{-j\omega t} \right]_{-\infty}^0 \end{aligned}$$



$$- \frac{1}{s-a} e^{-j\omega t} \quad \text{Re}\{s\} < a$$

Hence both  $e^{at} u(t)$  and  $-e^{-at} u(-t)$  have the same Laplace Transform, but different ROCs

Hence we need to know the ROC to invert the Laplace Transform

## NOTES.

In 2CJ4 we looked at the unilateral Laplace Transform

$$x(t) \xleftrightarrow{Lu} X(s) = \int_0^{\infty} x(t) e^{-st} dt$$

As I mentioned at that time, this year we will look at the bilateral case

$$x(t) \xleftrightarrow{L} X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

Why?

allows us to deal with non-causal systems and signals which start before  $t=0$

Consequences

Algebra + Properties very similar

However we need ROC + its properties

Need ROC to do inversion

## BILATERAL LAPLACE TRANSFORM

$$x(t) \longleftrightarrow X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt.$$

- Transform is not unique, and hence not invertible, unless you specify the Region of Convergence (ROC) i.e., the set of values of  $s$  for which integral converges.
- We now develop some properties of the ROC which make it easier to determine

### PROPERTIES OF ROC

$$X(s) = \frac{N(s)}{D(s)}$$

$s = \sigma + j\omega$ .

- Does not contain any poles.
- Since convergence of integral implies that  
 $I(\sigma) = \int |x(t)| e^{-\sigma t} dt < \infty$   
 The ROC depends only on  $\sigma$ . Hence it consists of a vertical strip in the  $s$ -plane

- ROC for a finite duration signal :

$$I(\sigma) = \int |x(t)| e^{-\sigma t} dt$$

Suppose  $x(t)$  is zero outside  $t \in [a, b]$   
 and that  $|x(t)| \leq M$

Then  $I(\sigma) \leq \int_a^b M e^{-\sigma t} dt$ .

$$\begin{cases} -\frac{A}{\sigma} e^{-\sigma t} \Big|_a^b & , \sigma \neq 0 \\ A(b-a) & \sigma = 0 \end{cases}$$

This is finite for all finite values of  $\sigma$

$\Rightarrow$  ROC of a finite duration signal is the whole s-plane

- ④ Infinitely long signals of "exponential order"  
(almost all practical signals are of exponential order)

Assume  $x(t) \leq Ae^{\sigma_0 t}, t > 0$

$$x(t) < Ae^{\sigma_n t}, t < 0$$

These bounds get tighter as  $A, \sigma_0$  get smaller,  
 $\sigma_n$  gets larger

What does  $I(\sigma)$  look like in these cases?

$$I(\sigma) = I_+(\sigma) + I_-(\sigma)$$

$$= \int_0^\infty |x(t)| e^{-\sigma t} dt + \int_{-\infty}^0 |x(t)| e^{-\sigma t} dt$$

$$\begin{aligned}
 I_-(\sigma) &= \int_{-\infty}^0 |x(t)| e^{-\sigma t} dt \\
 &\leq A \int_{-\infty}^0 e^{(\sigma_n - \sigma)t} dt \\
 &= \frac{A}{\sigma_n - \sigma} e^{(\sigma_n - \sigma)t} \Big|_{-\infty}^0
 \end{aligned}$$

Similarly,

$$\begin{aligned}
 I_+(\sigma) &= \int_0^\infty |x(t)| e^{-\sigma t} dt \\
 &\leq \frac{A}{\sigma_p - \sigma} e^{(\sigma_p - \sigma)t} \Big|_0^\infty
 \end{aligned}$$

Hence  $I_-(\sigma)$  is finite for  $\sigma < \sigma_n$ .

$I_+(\sigma)$  is finite for  $\sigma > \sigma_p$

$\Rightarrow$   $I(\sigma)$  is finite for  $\sigma_p < \sigma < \sigma_n$   
 (Note that this region may be empty!).

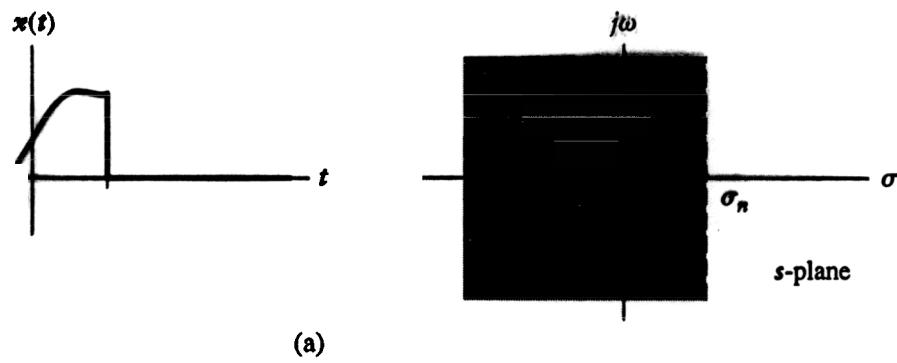
This allows us to make following conclusions

Left-sided signal,  $x(t)=0$  for  $t>b \Rightarrow$  ROC is  $\sigma < \sigma_n$ .

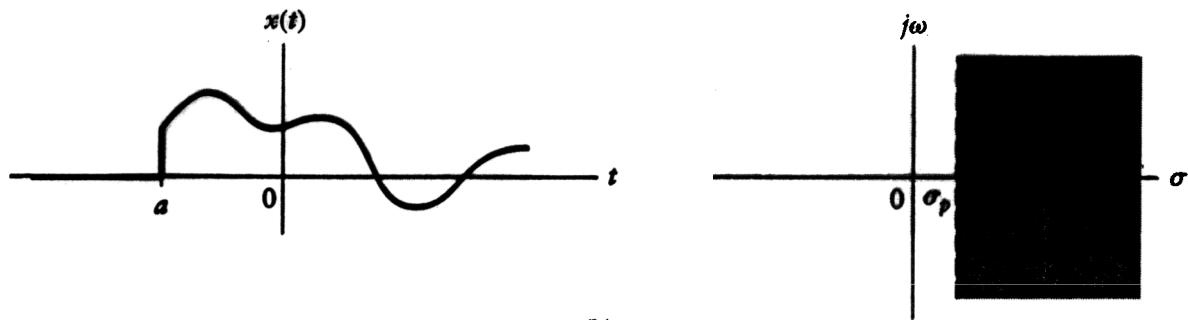
Right-sided signal,  $x(t)=0$  for  $t<a \Rightarrow$  ROC is  $\sigma > \sigma_p$

Two-sided signal  $\Rightarrow$  ROC is  $\sigma_p < \sigma < \sigma_n$

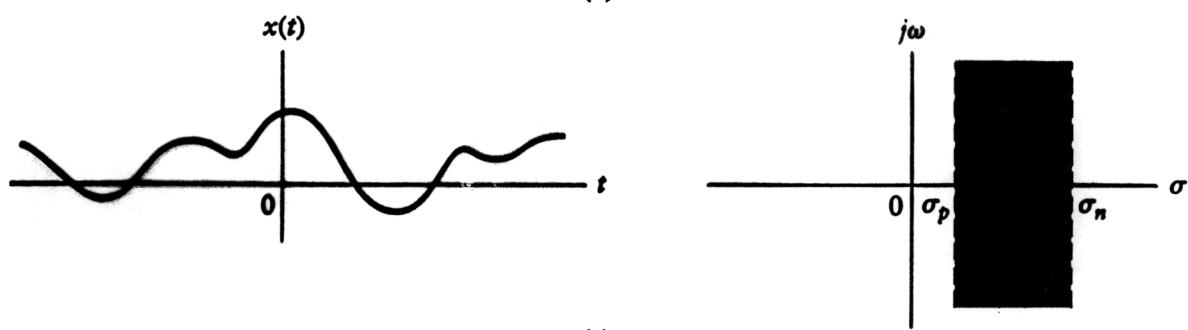
Fig 6.12



(a)



(b)



(c)

**FIGURE 6.12** Relationship between the time extent of a signal and the ROC. (a) A left-sided signal has ROC to the left of a vertical line in the  $s$ -plane. (b) A right-sided signal has ROC to the right of a vertical line in the  $s$ -plane. (c) A two-sided signal has ROC given by a vertical strip in the  $s$ -plane of finite width.

## EXAMPLE 6.12

Identify the ROC of

$$x_1(t) = e^{-2t} u(t) + e^{-t} u(-t)$$

$$x_2(t) = e^{-t} u(t) + e^{-2t} u(-t)$$

$$I_1(\sigma) = \int |x_1(t)| e^{-\sigma t} dt$$

$$= \int_{-\infty}^0 e^{-(1+\sigma)t} dt + \int_0^{\infty} e^{-(2+\sigma)t} dt$$

$$= \underbrace{\left[ \frac{-1}{1+\sigma} e^{-(1+\sigma)t} \right]_{-\infty}^0}_{\text{finite for } \sigma < -1} + \underbrace{\left[ \frac{-1}{2+\sigma} e^{-(2+\sigma)t} \right]_0^{\infty}}_{\text{finite for } \sigma > -2}$$

$\underbrace{\phantom{0}}$   
finite for  $\sigma < -1$

$\underbrace{\phantom{0}}$   
finite for  $\sigma > -2$

$$\Rightarrow \text{ROC is } -2 < \sigma < -1$$

Note that

$$X_1(s) = \frac{1}{s+1} + \frac{1}{s+2} = \frac{-1}{(s+1)(s+2)}$$

$\Rightarrow X_1(s)$  has poles at  $s = -1$  and  $s = -2$   
and these form the boundary of the ROC

For  $x_2(t)$ ,

$$I_2(\sigma) = \int_{-\infty}^0 e^{-(2+\sigma)t} dt + \int_0^{\infty} e^{-(1+\sigma)t} dt$$
$$= \underbrace{\frac{-1}{2+\sigma} e^{-(2+\sigma)t}}_{\text{finite for } \sigma < -2} \Big|_0^{-\infty} + \underbrace{\frac{-1}{1+\sigma} e^{-(1+\sigma)t}}_{\text{finite for } \sigma > -1} \Big|_0^{\infty}$$

$\Rightarrow$  ROC is  $\sigma < -2 \cap \sigma > -1$

$\Rightarrow$  There is no ROC.

$\Rightarrow X_2(s)$  does not exist anywhere.

However

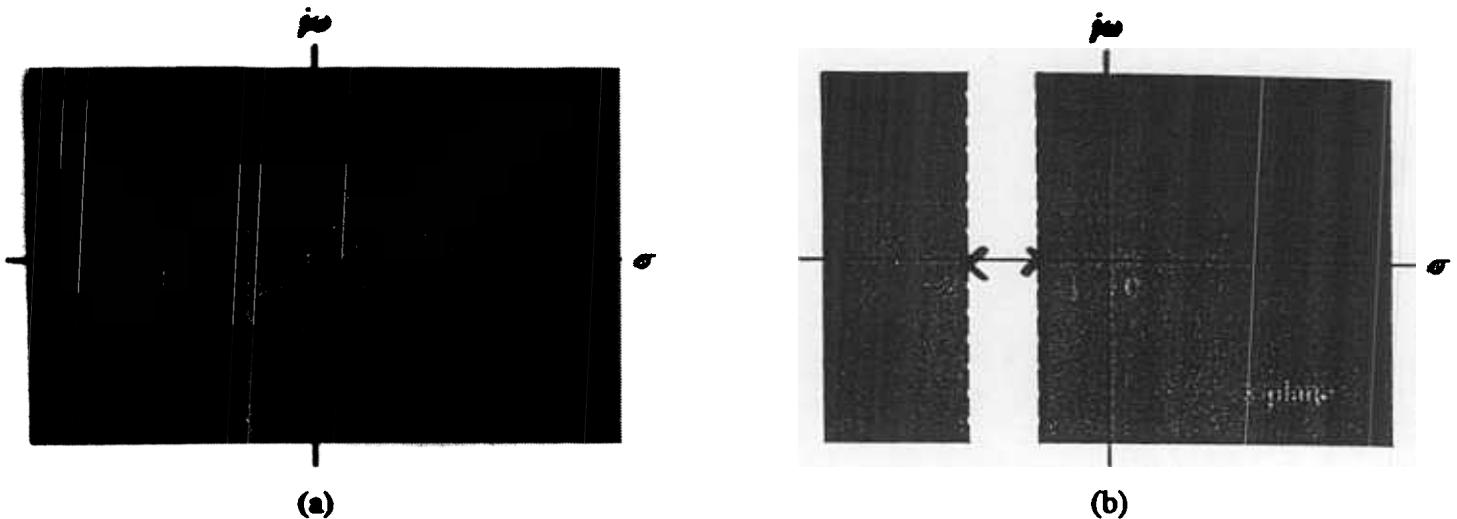
$$x_2(t) = e^{-t} u(t) + e^{-2t} u(-t)$$

and.

$$e^{-t} u(t) \leftrightarrow \frac{1}{s+1}, \text{ Re}\{s\} >$$

$$e^{-2t} u(-t) \leftrightarrow \frac{1}{s+2}, \text{ Re}\{s\} < -2.$$

\* Since ROC's are disjoint, Laplace transform of sum is not defined



**FIGURE 6.13** ROCs for signals in Example 6.12. (a) The shaded regions denote the ROCs of each individual term,  $e^{-2s}u(t)$  and  $e^{-t}u(-t)$ . The doubly shaded region is the intersection of the individual ROCs and represents the ROC of the sum. (b) The shaded regions represent the individual ROCs of  $e^{-2s}u(-t)$  and  $e^{-t}u(t)$ . In this case there is no intersection and the Laplace transform of the sum does not converge for any value of  $s$ .