

FOURIER REPRESENTATIONS OF SAMPLED SIGNALS.

If.

$$x_d(t) \xleftrightarrow{\text{FT}} X_d(j\omega),$$

$$x[n] = x_d(nT) \xleftrightarrow{\text{DTFT}} ?$$

- The answer to this question will lead us to a key result in sampling theory and practice
- We will first calculate the answer directly, and then the indirect method from the book. The indirect method uses some "non-physical" models, but is generally considered easier to understand.

DIRECT METHOD.

$$\begin{aligned}
 X(e^{j\Omega}) &= \sum_n x[n] e^{-j\Omega n} \\
 &= \sum_n x_d(nT) e^{-j\Omega n} \\
 &= \sum_n \frac{1}{2\pi} \int X_d(j\omega) e^{j\omega nT} d\omega e^{-j\Omega n} \\
 &= \frac{1}{2\pi} \int X_d(j\omega) \underbrace{\sum_n e^{j\omega nT} e^{-j\Omega n}}_{\text{DTFT of } e^{j\omega nT}} d\omega \\
 &= 2\pi \sum_k \delta(\Omega - \omega T - 2\pi k)
 \end{aligned}$$

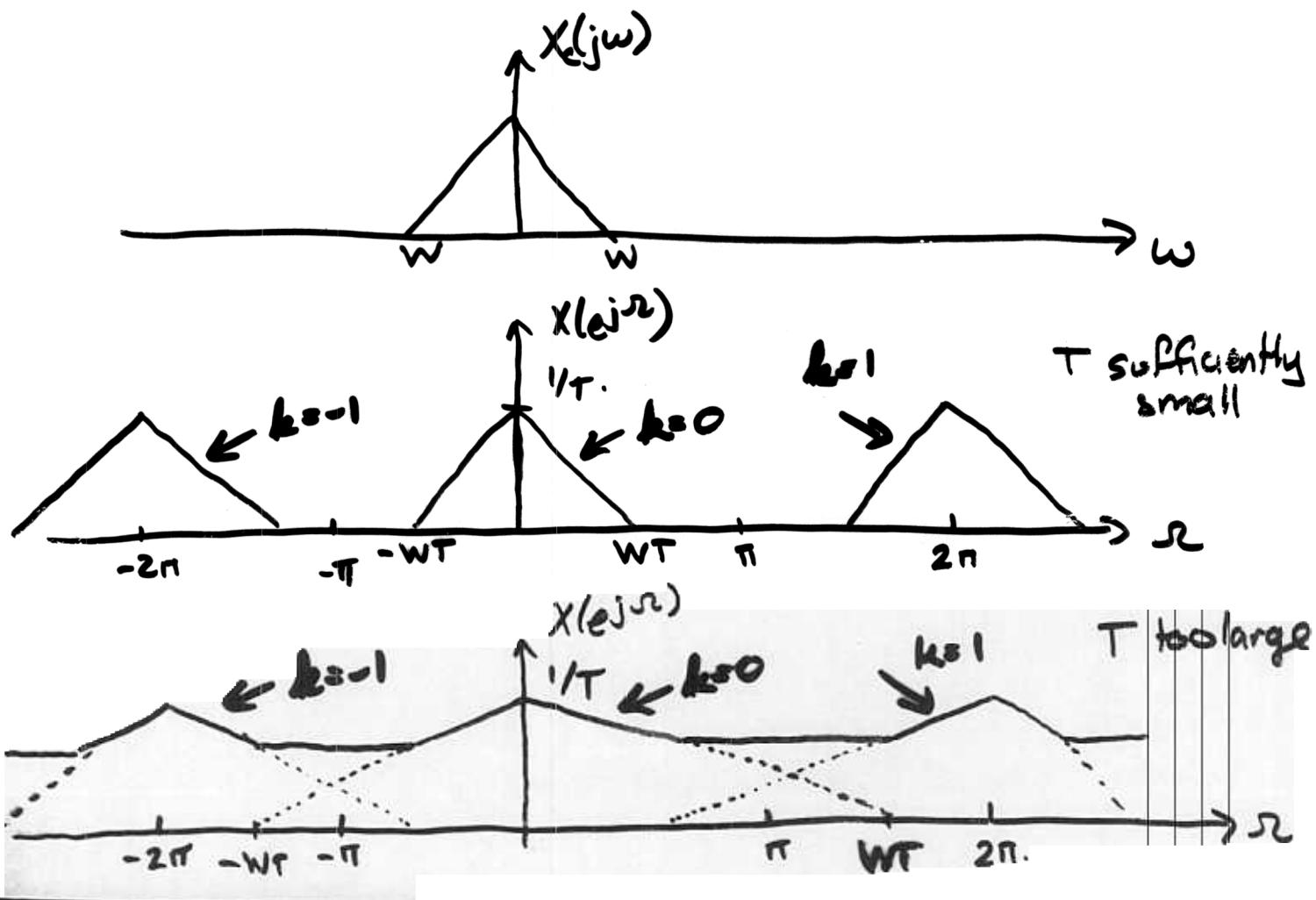
$$\Rightarrow X(e^{j\omega}) = \sum_k \int X_c(j\omega) \delta(\omega - 2\pi k) d\omega.$$

Let $\lambda = \omega + \omega T$

$$= \frac{1}{T} \sum_k \int X_c(j\frac{\lambda}{T}) \delta(\omega - \lambda - 2\pi k) d\lambda$$

$$= \sum_k X_c(j\frac{\omega - 2\pi k}{T})$$

$\Rightarrow X(e^{j\omega})$ can be constructed by taking $X(j\omega)$ Scaling it by $1/T$ and then shifting up and down the ω axis by $2\pi k$



- The model we have used here is direct, and uses physically realizable criteria everywhere.
- However the book takes the following indirect route
- First, we try to represent the discrete-time signal $x[n]$ in a continuous-time form

What continuous-time form should we choose?

Think of complex exponentials

$$x(t) = e^{j\omega t} \quad \text{and} \quad e^{j\omega nT} = g[n]$$

$$\text{if } g[n] = x(nT) \text{ then } \omega = \omega T$$

This gives us a hint

More formally we now want to find a continuous time function $x_g(t)$ such that.

$$x_g(t) \xleftrightarrow{\text{FT}} X_g(j\omega)$$

$$x[n] \xrightarrow{\text{DTFT}} X(e^{j\omega n})$$

$$\text{and } X_g(j\omega) = X(e^{j\omega n}) \quad \omega = \omega T$$

what is $x_g(t)$?

Well,

$$X_S(j\omega) = \sum_n x[n] e^{-j\omega Tn}$$

but from the time-shift property,

$$s(t-nT) \xrightarrow{\text{FT}} e^{-j\omega Tn}$$

$$\Rightarrow x_g(t) \sum_n x[n] s(t-nT) \xrightarrow{\text{FT}} X_S(j\omega) = \sum_n x[n] e^{-j\omega Tn}$$

That is, if we represent a discrete-time signal in continuous time by a weighted sequence of impulses we preserve the Fourier ~~to~~ representation.

Fig 4.17

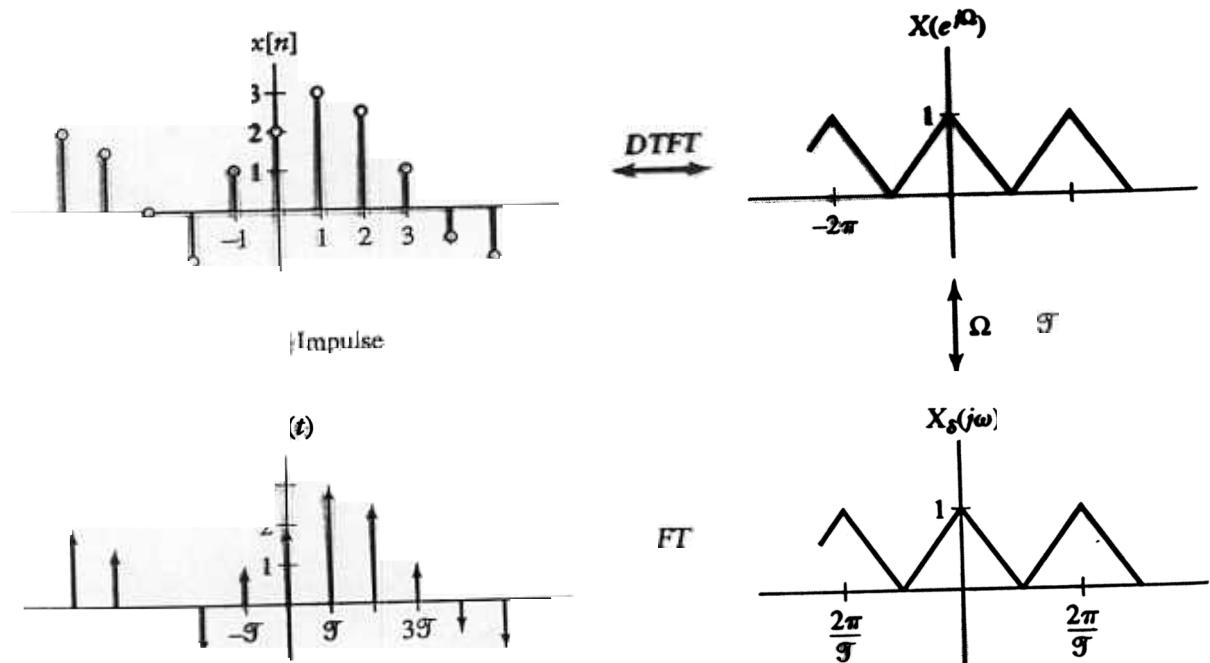


FIGURE 4. Relationship between DTFT and FT representations of discrete signal.

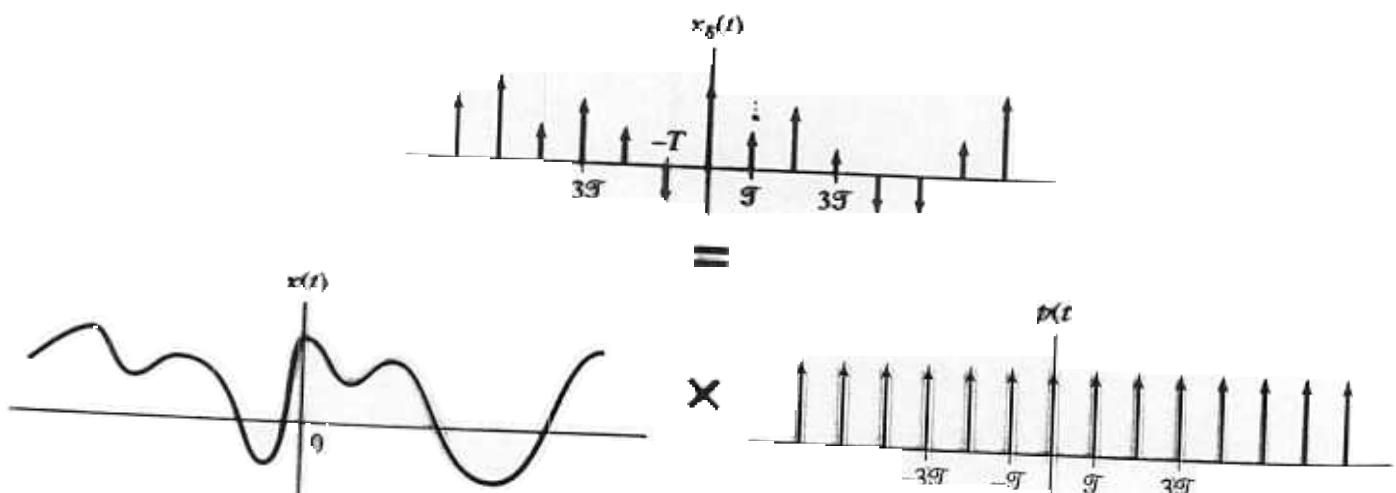


FIGURE 4.9 Mathematical representation of sampling as the product of given signal and impulse train.