

Lecture 6

From Sections 7.5-7.7, 8.5-8.7

Self read 8.6

Solve 7.31, 7.33, 7.34, 7.35, 7.37, 7.38,
7.41, 7.44, 7.50, 7.51, 8.26, 8.28,
8.31

Magnetic Flux

* $\underline{B} = \mu H$ is magnetic flux density
in Webers/m²

* μ_0 , permeability of free space
has the value $4\pi \times 10^{-7} \text{ W/m}$

* The magnetic flux through a
surface is $\Phi_m = \iint_S \underline{B} \cdot d\underline{s}$

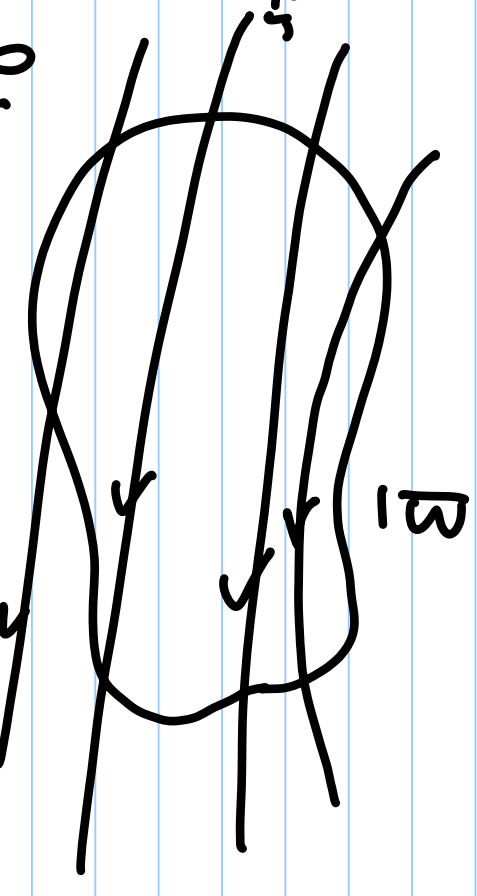
Magnetic Flux (Cont'd)

* There are no

magnetic charges

⇒ magnetic field

lines are closed lines



⇒

$$\oint \underline{B} \cdot d\underline{s} = 0 \Rightarrow \nabla \cdot \underline{B} = 0$$

Gauss Law for magnetostatics



Magnetic Vector Potential

* $\nabla \cdot \underline{B} = 0$ but $\nabla \cdot (\nabla \times \underline{A}) = 0$ for any vector \underline{A}

$\Rightarrow \underline{B} = \nabla \times \underline{A}$, where \underline{A} is the magnetic vector potential

* In some problems, it is easier to find \underline{A} and then find \underline{B}

(Note similarity with ∇ and \underline{E})

Equation Governing \underline{A}

$$\nabla \times \underline{H} = \underline{J} \quad (\text{Currents result in } \underline{H})$$

$$\nabla \times \left(\frac{\underline{B}}{\mu} \right) = \underline{J}$$

* If μ is constant, we can take it

$$\text{out} \Rightarrow \frac{1}{\mu} \nabla \times \underline{B} = \underline{J}$$

$$\Rightarrow \frac{1}{\mu} \nabla \times (\nabla \times \underline{A}) = \underline{J}$$

* We use the identity

$$\nabla \times \nabla \times \underline{A} = \nabla (\nabla \cdot \underline{A}) - \nabla^2 \underline{A}$$

Equation Governing A (Cont'd)

* We impose the condition $\nabla \cdot \underline{A} = 0$
in order to uniquely determine

A

* It follows that $\nabla^2 \underline{A} = -\underline{\rho} \underline{J}$

Note the similarity with Poisson's
equation $\nabla^2 V = -\frac{\rho V}{\epsilon}$

Analogy Examples

$$V = \frac{1}{4\pi\epsilon} \int_{\tilde{c}} \frac{\rho}{R} d\tilde{c} \iff \bar{A} = \frac{M}{4\pi} \int_{\tilde{c}} \frac{I d\tilde{c}}{R} \text{ wek } m$$

$$V = \frac{1}{4\pi\epsilon} \int_{\tilde{s}} \frac{\rho}{R} d\tilde{s} \iff \bar{A} = \frac{M}{4\pi} \int_{\tilde{s}} \frac{I \tilde{s}}{R} d\tilde{s}$$

$$V = \frac{1}{4\pi\epsilon} \int_{\tilde{v}} \frac{\rho_v}{R} d\tilde{v} \iff \bar{A} = \frac{M}{4\pi} \int_{\tilde{v}} \frac{I d\tilde{v}}{R}$$



Magnetization

* In a general material

$$\underline{B} = \mu_0 (\underline{H} + \underline{M})$$

* Magnetization in magnetic materials is similar to polarization in dielectric materials

* For linear materials, we have

$$\underline{M} = \chi_m \underline{H}$$

magnetic susceptibility

Magnetization (Cont'd)

* It follows that we have

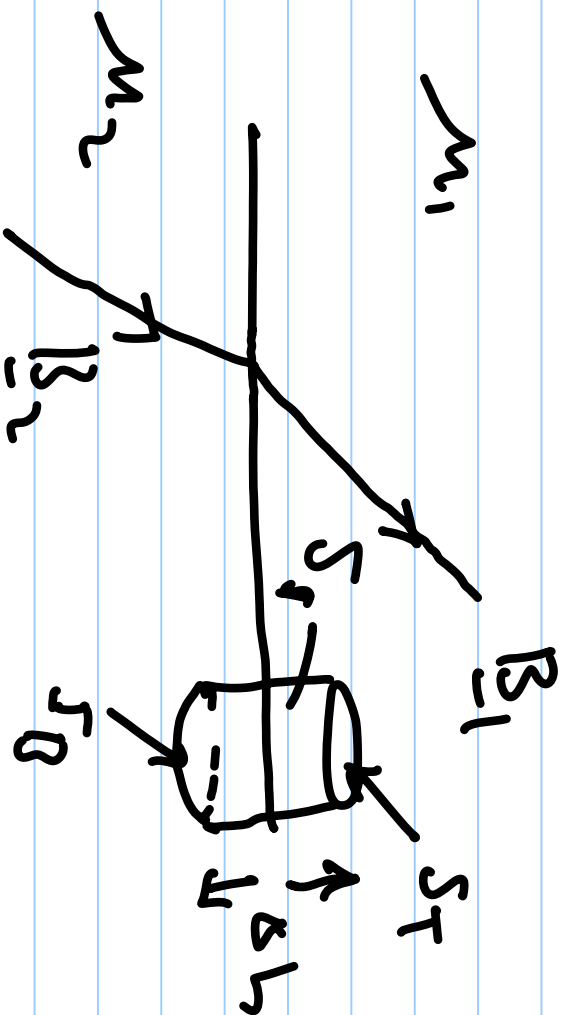
$$\underline{B} = \mu_0 (\underline{H} + \underline{M}) = \mu_0 (\underline{H} + \chi_m \underline{H})$$

$$\underline{B} = \mu_0 (1 + \chi_m) \underline{H} = \mu_0 \mu_r \underline{H}$$

* A material is defined by ϵ_r , μ_r ,
and σ



Magnetic Boundary Conditions



$$\oint \vec{B} \cdot d\vec{l} = 0 = \iint_{S_T} \vec{B} \cdot d\vec{l} + \iint_{S_B} \vec{B} \cdot d\vec{l} + \iint_{S_r} \vec{B} \cdot d\vec{l}$$

If $2h \rightarrow 0$, we have

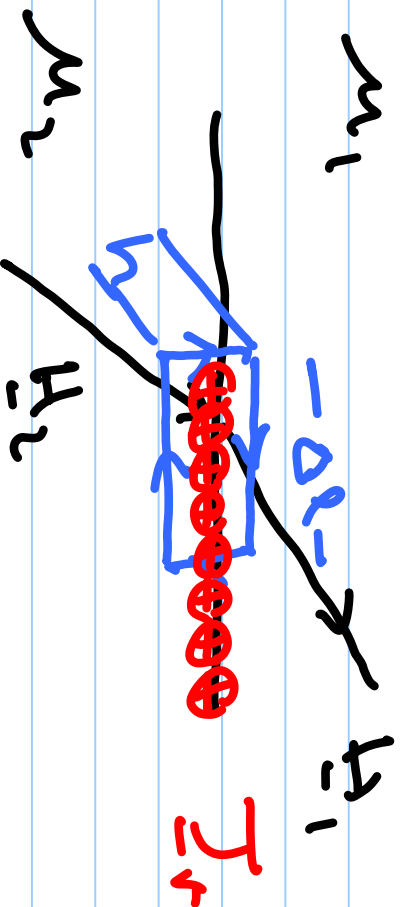
Boundary Conditions (Cont'd)

$$B_{y_1} \Delta S - B_{y_2} \Delta S = 0 \Rightarrow B_{y_1} = B_{y_2}$$

$$\Rightarrow \mu_1 H_{1n} = \mu_2 H_{2n}$$

Normal Component of H is
discontinuous

Boundary Conditions (Cont'd)



$$\oint \vec{H} \cdot d\vec{l} = I_{enc}$$

as $h \rightarrow 0$, the two side integrals
give zero

Boundary Conditions (Cont'd)

$$* H_{1T} \Delta l - H_{2T} \Delta l = \vec{J}_s \Delta l$$

$$H_{1T} - H_{2T} = \vec{J}_s$$

$$(H_1 - H_2) \times \hat{a}_{n12} = \vec{J}_s$$

* Note that a surface current

creates a discontinuity in the vector

\vec{H} in the normal direction \hat{a}_{n12}

