EE750 Advanced Engineering Electromagnetics Lecture 17

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2D FEM

• We consider a 2D differential equation of the form

$$-\frac{\partial}{\partial x}\left(\alpha_{x}\frac{\partial\varphi}{\partial x}\right)-\frac{\partial}{\partial y}\left(\alpha_{y}\frac{\partial\varphi}{\partial y}\right)+\beta\varphi=f,\ (x,y)\in\Omega$$

subject to
$$\varphi = p$$
 on Γ_1
 $\left(\alpha_x \frac{\partial \varphi}{\partial x} i + \alpha_y \frac{\partial \varphi}{\partial y} j\right) n + \gamma \varphi = q$ on Γ_2

where $\Gamma = \Gamma_1 \cup \Gamma_2$ is the contour enclosing the domain Ω and *n* is the unit outward normal

- Notice that the boundary conditions may be a Dirichlet, Neuman or mixed Dirichlet and Neuman.
- α_x , α_y and β are functions associated with the physical parameters and f is the excitation

2D FEM (Cont'd)

• The functional associated with this problem is

$$F(\varphi) = 0.5 \iint_{\Omega} \left[\alpha_x \left(\frac{\partial \varphi}{\partial x} \right)^2 + \alpha_y \left(\frac{\partial \varphi}{\partial y} \right)^2 + \beta \varphi^2 \right] d\Omega$$
$$- \iint_{\Omega} f\varphi \, d\Omega + \iint_{\Gamma_2} \left[\frac{\gamma}{2} \varphi^2 - q \varphi \right] d\Gamma$$

(Prove it)!

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2D FEM Analysis

- The computational domain is divided into triangles (elements)
- Each node has both a local and a global index



• A connectivity array n(i,e), i=1, 2, 3 and e=1, 2, ..., M stores the global indices of the nodes

i e	1	2	3
1	2	4	1
2	5	4	2
3	3	5	2
4	5	6	4





- We assume that there are M_s line segments on Γ_2
- We store the index array $n_s(i,s)$, i=1, 2 and $s=1, 2, ..., M_s$ of global indices of nodes on Γ_2

- The coordinates of the nodes $r_i = (x_i, y_i), i = 1, 2, ..., N$, where *N* is the total number of nodes
- The values of α_x , α_y , β and *f* for each element
- The value of p for each node residing on Γ_1
- The value of γ and q for each segment with nodes on Γ_2
- The two arrays n(i,e), i=1, 2, 3 and e=1, 2, ..., M and $n_s(i,s)$, i=1, 2 and $s=1, 2, ..., M_s$

Elemental Interpolation

- Over the *eth* element we utilize the linear approximation $\varphi^{e}(x, y) = a^{e} + b^{e} x + c^{e} y, \ (x, y) \in \Omega_{e}$
- The three nodes of the *e*th element must satisfy the linear interpolation relation $\varphi_1^e = a^e + b^e x_1^e + c^e y_1^e$, $\varphi_2^e = a^e + b^e x_2^e + c^e y_2^e$, $\varphi_3^e = a^e + b^e x_3^e + c^e y_3^e$
- Solving for a^e , b^e and c^e we obtain $\varphi^e(x, y) = \sum_{j=1}^3 N_j^e(x, y) \varphi_j^e$ where $N_j^e(x, y) = \frac{1}{2A_e} (a_j^e + b_j^e x + c_j^e y), j = 1, 2, 3$ $a_1^e = x_2^e y_3^e - y_2^e x_3^e, b_1^e = y_2^e - y_3^e, c_1^e = x_3^e - x_2^e$ $a_2^e = x_3^e y_1^e - y_3^e x_1^e, b_2^e = y_3^e - y_1^e, c_2^e = x_1^e - x_3^e$ $a_3^e = x_1^e y_2^e - y_1^e x_2^e, b_3^e = y_1^e - y_2^e, c_3^e = x_2^e - x_1^e$

• A_e is the area of the *e*th element and is given by

$$A_{e} = \frac{1}{2} \begin{vmatrix} 1 & x_{1}^{e} & y_{1}^{e} \\ 1 & x_{2}^{e} & y_{2}^{e} \\ 1 & x_{3}^{e} & y_{3}^{e} \end{vmatrix}$$

• The interpolation functions satisfy

$$N_{i}^{e}(x_{j}^{e}, y_{j}^{e}) = \delta_{ij} = \begin{cases} 1, \ i = j \\ \\ 0, \ i \neq j \end{cases}$$

The Homogenous Neuman BC case

- We first consider the case ($\gamma = q = 0$)
- The functional is expressed as a sum of elemental subfunctions

$$F(\boldsymbol{\varphi}) = \sum_{e=1}^{M} F^{e}(\boldsymbol{\varphi}^{e})$$

where

$$F^{e}(\varphi^{e}) = 0.5 \iint_{\Omega_{e}} \alpha_{x} \left(\frac{d \varphi^{e}}{dx}\right)^{2} + \alpha_{y} \left(\frac{d \varphi^{e}}{dy}\right)^{2} + \beta \left(\varphi^{e}\right)^{2} d\Omega - \iint_{\Omega_{e}} f \varphi^{e} d\Omega$$

• Substituting with the linear interpolation expression, we write

$$F^{e}(\varphi^{e}) = 0.5 \iint_{\Omega_{e}} \sum_{i=1}^{3} \sum_{j=1}^{3} \alpha_{x} \varphi_{i}^{e} \frac{d N_{i}^{e}}{dx} \frac{d N_{j}^{e}}{dx} \varphi_{j}^{e} + \alpha_{y} \varphi_{i}^{e} \frac{d N_{i}^{e}}{dy} \frac{d N_{j}^{e}}{dy} \varphi_{j}^{e} d\Omega$$
$$+ \iint_{\Omega_{e}^{i=1}} \sum_{j=1}^{3} \beta \varphi_{i}^{e} N_{i}^{e} N_{j}^{e} \varphi_{j}^{e} d\Omega - \iint_{\Omega_{e}} f \sum_{i=1}^{3} N_{i}^{e} \varphi_{i}^{e} d\Omega$$
$$\frac{\bigcup_{\Omega_{e}} \varphi_{i}^{e}}{\partial \varphi_{i}^{e}} = \sum_{j=1}^{3} \varphi_{j}^{e} \left(\iint_{\Omega_{e}} \alpha_{x} \frac{d N_{i}^{e}}{dx} \frac{d N_{j}^{e}}{dx} + \alpha_{y} \frac{d N_{i}^{e}}{dy} \frac{d N_{j}^{e}}{dy} + \beta N_{i}^{e} N_{j}^{e} d\Omega \right)$$
$$- \iint_{\Omega_{e}} f N_{i}^{e} d\Omega \qquad i=1, 2, 3$$
$$\left\{ \frac{\partial F^{e}}{\partial \varphi^{e}} \right\}_{3 \times 1} = \left[\mathbf{K}^{e} \right]_{3 \times 3} \left[\varphi^{e} \right]_{3 \times 1} - \left[\mathbf{b}^{e} \right]_{3 \times 1}$$

$$K_{ij}^{e} = \iint_{\Omega_{e}} \alpha_{x} \frac{d N_{i}^{e}}{dx} \frac{d N_{j}^{e}}{dx} + \alpha_{y} \frac{d N_{i}^{e}}{dy} \frac{d N_{j}^{e}}{dy} + \beta N_{i}^{e} N_{j}^{e} d\Omega$$

$$b_{i}^{e} = \iint_{\Omega_{e}} f N_{i}^{e} d\Omega \qquad i=1, 2, 3 \text{ and } j=1, 2, 3$$

• If α_x , α_y , β and *f* are taken as constants over each element, and utilizing the property

$$\iint_{\Omega_{e}} (N_{1}^{e})^{l} (N_{2}^{e})^{m} (N_{3}^{e})^{n} d\Omega = 2 A_{e} \frac{l!m!n!}{l!+m!+n!}$$

we get

$$K_{ij}^{e} = \frac{1}{4A_{e}} \left(\alpha_{x}^{e} b_{i}^{e} b_{j}^{e} + \alpha_{y}^{e} c_{i}^{e} c_{j}^{e} \right) + \frac{A_{e}}{12} \beta^{e} (1 + \delta_{ij})$$

$$b_{i}^{e} = \frac{A_{e}}{3} f^{e}$$

• The process of assembly involves storing the local elemental components into their proper location in the global system of equations

$$\frac{\partial F}{\partial \boldsymbol{\varphi}} = \mathbf{0} \quad \square \qquad [\boldsymbol{K}]_{N \times N} [\boldsymbol{\varphi}]_{N \times 1} = [\boldsymbol{b}]_{N \times 1}$$

- The element K_{ij}^{e} is added to $K_{n(i,e),n(j,e)}$
- The element b_i^e is added to $b_{n(i,e)}$



- There are six nodes $\implies K \in \Re^{6 \times 6}$ and $b \in \Re^{6 \times 1}$
- We initialize *K* and *b* with zeros
- Evaluate $K^{(1)}$ and $b^{(1)}$ an add them to the proper locations to get

An Assembly Example (Cont'd)

• Evaluate $K^{(2)}$ and $b^{(2)}$ an add them to the proper locations

$$\boldsymbol{K} = \begin{bmatrix} K_{33}^{(1)} & K_{31}^{(1)} & 0 & K_{32}^{(1)} & 0 & 0 \\ K_{13}^{(1)} & K_{11}^{(1)} + K_{33}^{(2)} & 0 & K_{12}^{(1)} + K_{32}^{(2)} & K_{31}^{(2)} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ K_{23}^{(1)} & K_{21}^{(1)} + K_{23}^{(2)} & 0 & K_{22}^{(1)} + K_{22}^{(2)} & K_{21}^{(2)} & 0 \\ 0 & K_{13}^{(2)} & 0 & K_{12}^{(2)} + K_{22}^{(2)} & K_{11}^{(2)} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}, \quad \boldsymbol{b} = \begin{bmatrix} b_{3}^{(1)} \\ b_{1}^{(1)} + b_{3}^{(2)} \\ 0 \\ b_{2}^{(1)} + b_{2}^{(2)} \\ b_{1}^{(2)} \\ b_{1}^{(2)} \\ b_{1}^{(2)} \end{bmatrix}$$

• Repeat the same steps for all elements

Incorporating a Boundary Condition of the 3rd Kind

- In this case γ and q are not zeroes The extra subfunctional $F_b(\varphi) = \iint_{\Gamma_2} \left[\frac{\gamma}{2} \varphi^2 q \varphi \right] d\Gamma$ is added to the functional F
- Because Γ_2 is comprised of M_s line segments, we may write $F_b(\varphi) = \sum_{s=1}^{M_s} F_b^s(\varphi^s)$
- We approximate the function φ over the segment s by the linear expression $\varphi^s = \sum_{i=1}^{s} N_j^s \varphi_j^s$, $N_1^s = 1 - \xi$, $N_2^s = \xi$

• ξ is the normalized distance from node 1 to node 2 EE750, 2003, Dr. Mohamed Bakr

 $\backslash \quad s$

$$F_{b}^{s}(\varphi) = \int_{s} \left[\frac{\gamma}{2} \varphi^{2} - q \varphi \right] d\Gamma$$

$$\bigcup \text{ Use the expansion}$$

$$F_{b}^{s}(\varphi) = \int_{s} \left(\frac{\gamma}{2} \sum_{i=1}^{2} \sum_{j=1}^{2} \varphi_{i}^{s} N_{i}^{s} N_{j}^{s} \varphi_{j}^{s} - q \sum_{i=1}^{2} N_{i}^{s} \varphi_{i}^{s} \right) d\Gamma$$

$$\bigcup \text{ Differentiate and use d } \Gamma = l^{s} d\xi$$

$$\frac{\partial}{\partial} F_{b}^{s} = \sum_{j=1}^{2} \varphi_{j}^{s} \int_{0}^{1} \gamma N_{i}^{s} N_{j}^{s} l^{s} d\xi - \int_{0}^{1} q N_{i}^{s} l^{s} d\xi, \quad i = 1, 2$$
in matrix form
$$\frac{\partial}{\partial} F_{b}^{s} = \left[\mathbf{K}^{s} \right]_{2 \times 2} \left[\varphi^{s} \right]_{2 \times 1} - \left[\mathbf{b}^{s} \right]_{2 \times 1}$$

$$K_{ij}^{s} = \int_{0}^{1} \gamma N_{i}^{s} N_{j}^{s} l^{s} d\xi, \quad b_{i}^{s} = \int_{0}^{1} q N_{i}^{s} l^{s} d\xi, \quad i = 1, 2 \text{ and } j = 1, 2$$

• Assembly is then applied to store these coefficients

The Dirichlet Boundary Condition

• The Dirichlet boundary conditions are imposed by eliminating the known nodes by substituting for their values

$$\begin{bmatrix} \boldsymbol{K}_{pp} & \boldsymbol{K}_{pu} \\ \boldsymbol{K}_{up} & \boldsymbol{K}_{uu} \end{bmatrix} \begin{bmatrix} \boldsymbol{\varphi}_{p} \\ \boldsymbol{\varphi}_{u} \end{bmatrix} = \begin{bmatrix} \boldsymbol{b}_{p} \\ \boldsymbol{b}_{u} \end{bmatrix}$$
 Original system
$$\begin{bmatrix} \boldsymbol{V}_{p} & \boldsymbol{K}_{uu} \end{bmatrix} \begin{bmatrix} \boldsymbol{\varphi}_{p} \\ \boldsymbol{\varphi}_{u} \end{bmatrix} = \begin{bmatrix} \boldsymbol{b}_{p} \\ \boldsymbol{b}_{u} \end{bmatrix}$$
 Reduced system

An Example: A Shielded Microstrip Line



- The microstrip is kept at potential $\varphi=1$ while the external shielding box is kept at potential $\varphi=0$
- Symmetry may be employed to reduce the computational domain by one half
- The governing BVP is

$$-\frac{\partial}{\partial x}\left(\varepsilon_r\frac{\partial\varphi}{\partial x}\right) - \frac{\partial}{\partial y}\left(\varepsilon_r\frac{\partial\varphi}{\partial y}\right) = \frac{\rho_c}{\varepsilon_o}$$

with $\varphi = 0$ on the outer conductor, $\varphi = 1$ on the microstrip and $\partial \varphi / \partial n = 0$ on the plane of symmetry

- It follows that we have $\alpha_x = \alpha_y = \varepsilon_r$, $\beta = 0, f = 0$
- The electric field is obtained through $E = -\nabla \varphi$. But φ over each element is approximated by $\varphi^{e}(x, y) = \sum_{j=1}^{3} N_{j}^{e}(x, y) \varphi_{j}^{e}, \quad N_{j}^{e}(x, y) = \frac{1}{2A_{e}} (a_{j}^{e} + b_{j}^{e}x + c_{j}^{e}y), \quad j = 1, 2, 3$ \downarrow $E = -\frac{\partial \varphi}{\partial x} i - -\frac{\partial \varphi}{\partial y} j = -\frac{1}{2A_{e}} \sum_{j=1}^{3} (b_{j}^{e}i + c_{j}^{e}j) \varphi_{j}^{e}$ Over the *e*th element

An Example: A Shielded Microstrip Line (Cont'd)



The Finite Element Method in Electromagnetics, Jianming Jin

An Example: A Shielded Microstrip Line (Cont'd)



The equi-potential lines